Earth-Venus-Earth Modem

Design Description and Interface Control Document

Rev C - DRAFT

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DSES

October 2026

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Earth-Venus-Earth Modem — Design Description and Interface Control Document

Document	DSES EVE Modem Design and ICD
Revision	Rev C — DRAFT, updated from the implementation; station reference decided
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Prepared by	Rick Hambly, K0GD, Deep Space Exploration Society
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Waveform design	Pete Wyckoff, KA3WCA, Open Research Institute ("Venus Bounce Transmitter Spiral #2")
Status	Design baseline; parameters marked TBC await confirmation from ORI. Rev C records what building the modem taught (2026-09-11): the frame-numbering and chunk-table semantics, what the pilot can and cannot do, the two-stage receive front end, the arming lead the radio needs, and the state of the validation plan through the B210 loopback bench; it also settles the station time and frequency reference after the Haswell rubidium and NTP server failed (2026-09-12): a Leo Bodnar GPS reference clock that the modem programs and checks itself, proven on the bench with the B210 locked and timed from it and its transmit frequency within 0.03 Hz of the lab reference (7.1, D23, O3; O16 closed, stage 4 complete). Rev B (2026-09-11) carried the team review comments of Michelle Thompson and Alex Nersesian

This document describes the DSES implementation of the ORI Earth-Venus-Earth (EVE) waveform for the Venus inferior conjunction of 24 October 2026, and it defines every interface the implementation touches: the signal on the air, the station hardware, the timing and frequency references, the files exchanged with other stations, and the boundary with the DSES Radio Astronomy Workbench. Sections 1 through 5 are the design description. Sections 6 through 9 are the interface control document (ICD). Section 10 is the decision and open-issue register. The operator's instructions are a separate, shorter document, `DSES_EVE_Modem_Operators_Guide` (also the application's Help), so that the person at the keyboard is not handed forty pages of design. Anything in this document that another team member depends on is in the ICD sections, so that a change there is a change everyone sees.

The ORI reference material is the EVE repository on GitHub (OpenResearchInstitute/EVE): the MATLAB simulation in `signal_design/` (May–June 2026), the Python transmit generator in `signal_design/Python_Implementation/` (August 2026, the current implementation per ORI), the ORI link budget notebook, and the CAMRAS validation white paper. All ORI code is GPL-3.0 and is credited to Pete Wyckoff and ORI wherever it is used.

1. Purpose and summary

The DSES 60-foot dish at Haswell, Colorado, will attempt to bounce a digital message off Venus near inferior conjunction and decode the echo. ORI designed the waveform and validated it in simulation, and ORI has a transmit-side generator that writes the waveform to a SigMF file for playback through a USRP B210 in GNU Radio. ORI had no receiver when this document was started; a receiver by the DEFCON group working with ORI was under over-the-air test as of 10 September and is expected in the ORI repository (O14). DSES still needs a complete, runnable modem: a transmitter that fits the DSES station's duty cycle and keying, a receiver that decodes echoes, and the synchronization, Doppler, and scheduling machinery that the reference design assumes away.

The design decisions in this revision:

- **The modem streams.** The transmitter synthesizes the waveform on the fly, driven by a schedule, rather than playing a pre-generated file. SigMF export and import are retained for interoperability with ORI's files, for bench tests, and for sharing with other stations, but they are not how the station transmits (section 3).
- **The 2026 Venus attempt is a 23 cm operation at 1299.5 MHz.** The 13 cm package will not be ready this year, so DSES transmits with the 23 cm package retuned from 1296 to 1299.5 MHz, the frequency Dwingeloo, Stockert, and Effelsberg use. The modem is frequency-agile (1296, 1299.5, 2304, 2400 MHz, and others); every frequency-dependent quantity is computed per schedule (section 2.4).
- **Monostatic operation is the baseline**, with reception by a European station as the upside case at 1299.5 MHz. Computed with ORI's own link-budget classes at the 2026 distance, the 23 cm monostatic link with the station's 1200 W amplifier is 4.2 dB below the design point at ORI's static Venus albedo and 5.4 dB below at ORI's date-resolved albedo for conjunction (section 2.2); the DSES matched-bin variant, repeat-and-combine over a session, and any European receiver each claw part of that back.
- **The B210 drives the 23 cm amplifier directly.** The EVE25 package's built-in transverter covers only 1296 to 1298 MHz, so it is bypassed: the B210 generates 1299.5 MHz, a 20 W driver in the control room sends it down 8.8 dB of LMR-600 to the feed (measured 2026-10-10), where the 1200 W SSPA's own pre-driver makes full power from 2 W; the SSPA covers 1280 to 1300 MHz (Alex Nersesian, 10 September; Rick, 28 September; sections 2.3 and 7.1).
- **A DSES-only 23 cm variant of the waveform is defined** (Variant B: 1.5 Hz bins matched to the 23 cm Doppler spread, same symbol length), worth about 1.1 dB and selectable per schedule. ORI's waveform (Variant A) remains the interoperable one (sections 2.4, 6.1).
- **The message is the station callsign, K0PRT K0PRT**, 11 characters, exactly the 90-bit field. It is a schedule parameter, never a code change (section 4.1).

- **EME testing needs no power amplifier.** The B210's own output into the dish gives a C/N0 of +12 dB-Hz at 1296 MHz and +16 dB-Hz at 2304 MHz off the Moon, so both bands can be tested at and below the design point before either amplifier exists (section 4.6).
- **The 30-minute message is sent in chunks** of up to the Earth-Venus round-trip time (272 s on 24 October), with the station listening for the echo of each chunk while the amplifier cools. The chunk length is a parameter; 4 minutes is the working value, giving one message in about 64 minutes at 47 percent transmit duty (section 4).
- **The ORI Python generator's conventions are the air-interface specification** (section 6). They differ from the earlier MATLAB simulation in bin width, frame count, bit order, and comb placement; ORI confirmed on 9 September that the MATLAB was early simulation and the Python is the current implementation. Two numerical inconsistencies in the Python are resolved here by definition and flagged TBC.
- **The modem is a separate project from the Workbench.** It reuses the Workbench's proven B210 code by factoring that code into an importable module (section 5 and section 9).
- **Doppler is handled on both ends**: ephemeris pre-compensation on transmit so the echo arrives at the nominal frequency, and residual tracking on receive. On conjunction day the two-way Doppler rate at Haswell reaches 0.48 Hz/s, which is 14 tone spacings across one symbol if left uncorrected (section 4.4).
- **Timing comes from GPS**, not a maser. A non-coherent receiver only needs to know which 0.35-second frame belongs to which symbol; GPS time on the B210 and a shared UTC epoch provide that to a millisecond (section 4.3).
- **Validation runs simulation first, then B210 loopback, then a low-power Earth-Moon-Earth test, then Venus** (section 5.4). As of 2026-09-12 the modem is implemented through the B210 loopback bench: the whole chain from schedule to offline decode ran on the bench radio with both message passes decoded (section 5.4).

The waveform is ORI's: Pete Wyckoff, KA3WCA, designed it and Michelle Thompson wrote the Python implementation that defines the air interface; DSES built the station side, the receiver and the operations around it. The Acknowledgments at the end say what we owe them.

2. Mission context

2.1 Geometry on conjunction day

Computed for Haswell (38.3808° N, 103.1561° W, 1311 m) with astropy's built-in ephemeris; the flight software will use a JPL Horizons table for the operational numbers.

Quantity	2026-10-24	Notes
Earth-Venus distance	0.273 AU (40.8 million km)	Minimum of the apparition
Round-trip light time	272 s (4.5 min)	Sets the maximum monostatic chunk length
Venus above 20° at Haswell	15:30 – 21:15 UTC (5.75 h)	Rises 13:25, sets 23:30 UTC
Maximum elevation	34° at 18:30 UTC	
Angular separation from the Sun	about 6°	Solar noise in the sidelobes raises Tsys; quantify in the link budget
Two-way Doppler shift	1299.5 MHz: +5.3 → −2.5 kHz; 2304 MHz: +9.5 → −4.5 kHz; zero at 19:50 UTC	Scales with frequency
Two-way Doppler rate	1299.5 MHz: up to −0.27 Hz/s; 2304 MHz: up to −0.48 Hz/s (18:30 UTC)	45 Hz (8 tone spacings) or 79 Hz (14) across one 165 s symbol

Venus stays within 10 percent of minimum distance from 7 October to 12 November, so the attempt is a multi-week window, not one day. The round-trip time and Doppler numbers above change slowly over that window and the schedule generator recomputes them per session.

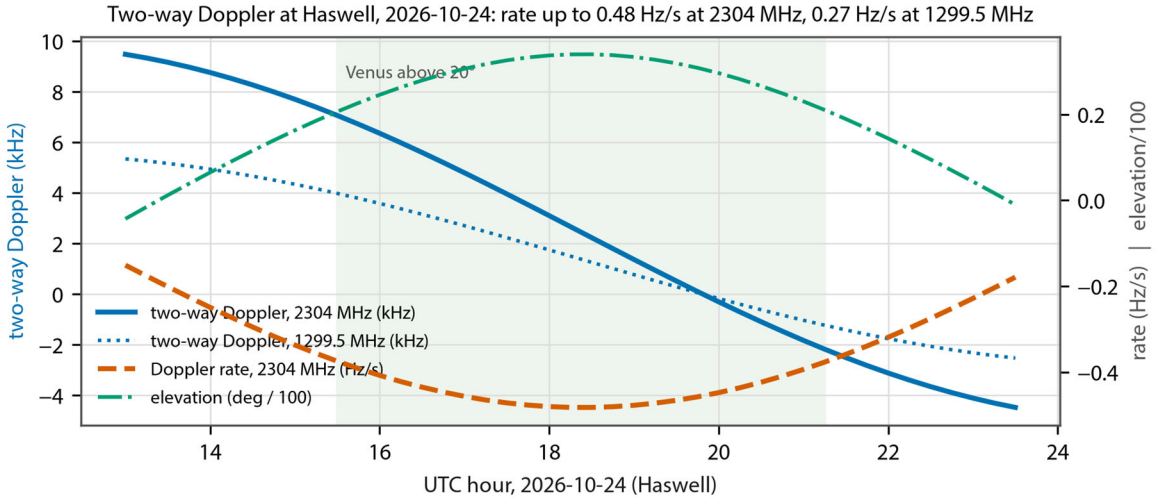


Figure 1 — Two-way Doppler shift at 2304 and 1299.5 MHz, Doppler rate at 2304 MHz, and Venus elevation at Haswell on 24 October 2026. The shaded band is the working window above 20 degrees; at 1299.5 MHz the rate scales by 0.56.

2.2 Link budget

Every row below is computed with ORI's link-budget classes, extracted verbatim from the ORI notebook into `link_budget/ori_link_budget.py` and driven by `link_budget/dses_cases.py` in this project, so the table is reproducible with one command when a station number changes. Inputs: the ORI site dataclasses

(DSES 18.29 m at 69 percent, 0.5 dB line losses, 0.4 dB LNA, 30° elevation; Dwingeloo 25 m; Effelsberg 100 m, receive only), ORI's system noise model, ORI's static Venus radar albedo 0.152, clear sky, and the Earth-Venus distance of 2026-10-24, 40.8 million km. That distance agrees with the notebook's own ephemeris: its date-resolved cells compute the Earth-Venus distance with Skyfield and JPL Horizons, 40.81 million km on 2026-10-25 (Michelle Thompson, 2026-09-10). Only the notebook's opening printout, which brackets the orbit at 38 and 261 million km, is at a fixed distance; the anchor row reproduces that printout to show the extraction is faithful, and the 2.8 million km between the bracket and conjunction day is worth 1.2 dB.

Case (2026-10-24 distance unless noted)	C/N0 (dB-Hz)	Tsys (K)	Margin to 0 dB-Hz	Basis
DSES monostatic, 2304 MHz, 1500 W, at the notebook's 38 million km	+1.7	76	+1.7	anchor: reproduces the notebook's +1.67
DSES monostatic, 2304 MHz, 1500 W	+0.4	76	+0.4	13 cm package, next apparition
DSES monostatic, 2400 MHz, 1500 W	+0.7	78	+0.7	13 cm alternative band
DSES monostatic, 1299.5 MHz, 1500 W	−3.3	57	−3.3	23 cm, for comparison: the station amplifier is rated 1200 W
DSES monostatic, 1299.5 MHz, 1200 W	**−4.2**	57	−4.2	**23 cm package: SSPA rated 1200 W CW (Alex Nersesian, 2026-09-10); power delivered at 1299.5 MHz TBC (O2)**
DSES monostatic, 1299.5 MHz, 1000 W	−5.0	57	−5.0	23 cm, if the amplifier delivers less than rated
DSES monostatic, 1299.5 MHz, 500 W	−8.0	57	−8.0	23 cm, half power
Dwingeloo monostatic, 1299.5 MHz, 1000 W (cross-check)	−0.9	76	−0.9	CAMRAS measured +0.65 in March 2025: the model is about 1.5 dB conservative
DSES 1200 W transmits, Dwingeloo 25 m receives	−2.8	76	−2.8	Stockert (25 m) similar

Case (2026-10-24 distance unless noted)	C/N0 (dB-Hz)	Tsys (K)	Margin to 0 dB-Hz	Basis
DSES 1000 W transmits, Dwingeloo 25 m receives	−3.6	76	−3.6	
DSES 1200 W transmits, Effelsberg 100 m receives	+10.9	52	+10.9	opportunistic; ORI's Effelsberg proposal
DSES 1000 W transmits, Effelsberg 100 m receives	+10.1	52	+10.1	
2028 apparition, 44.5 million km: DSES monostatic, 2304 MHz, 1500 W	−1.1	76	−1.1	13 cm package; a week either side of conjunction
2028: DSES monostatic, 2400 MHz, 1500 W	−0.8	78	−0.8	
2028: DSES monostatic, 1299.5 MHz, 1500 W	−4.8	57	−4.8	23 cm, for comparison
2028: DSES 1500 W at 2304 MHz transmits, Effelsberg receives	+13.9	73	+13.9	

Venus albedo. The rows above use the notebook's static radar albedo, 0.152, the value behind the CAMRAS cross-check. The notebook now also integrates the Magellan reflectivity map over the hemisphere facing Earth on each date (its "Spatially-Resolved" and "Dynamic Venus Radar Albedo" cells). For the October 2026 conjunction the sub-Earth point falls on plains and the effective albedo is 0.117, 1.1 dB below the static value; the notebook's own sensitivity sweep shows the result barely depends on the backscatter model (0.15 dB from Lambertian to near-specular). DSES carries both: 0.152 as the validated planning value and 0.117 as the physically motivated pessimistic case (D17, O15).

Case, 2026-10-24	Albedo 0.152 (static)	Albedo 0.117 (date-resolved)	Difference
DSES monostatic, 2304 MHz, 1500 W	+0.4 dB-Hz	−0.7 dB-Hz	−1.1 dB
DSES monostatic, 1299.5 MHz, 1500 W	−3.3	−4.4	−1.1
DSES monostatic, 1299.5 MHz, 1200 W	**−4.2**	**−5.4**	−1.1
DSES monostatic, 1299.5 MHz, 1000 W	−5.0	−6.2	−1.1
DSES monostatic, 1299.5 MHz, 500 W	−8.0	−9.2	−1.1

Pete Wyckoff sized the waveform for C/N0 = 0 dB-Hz. Read against that:

- **13 cm, when that package exists**, closes with under a decibel of margin at the 2026 distance; the notebook's +1.7 dB was at a shorter range than the conjunction offers.

- **23 cm in 2026 does not close in a single monostatic pass.** With the station's 1200 W amplifier the shortfall is 4.2 dB, or 5.4 dB at the date-resolved albedo, before solar noise. Three things recover it, and the plan uses all three: the DSES Variant B waveform is worth about 1.1 dB (section 2.4); repeat-and-combine over five passes in the 5.75-hour window is worth 7 dB (section 4.5); and any European station receiving with the DSES schedule file changes the picture on its own, Dwingeloo or Stockert by 1.4 dB and Effelsberg by 15 dB.
- **The model is conservative.** Its Dwingeloo prediction is 1.5 dB below what CAMRAS measured in March 2025, so the DSES rows may be pessimistic by a similar amount. That is margin to hope for, not to plan on.
- **Every decibel of the transmit chain matters at 23 cm**: the power the amplifier actually delivers at 1299.5 MHz, which sits 0.5 MHz inside the top of its 1280 to 1300 MHz range, under the chunk duty cycle (1200 W rated; 500 W would cost 3.8 dB), the 20 W driver's headroom, the feed match, and the receiver Tsys are the open items that decide where in the table DSES lands (O2, O4).

Will monostatic 23 cm succeed in 2026? Yes, on the model, provided the 23 cm amplifier delivers close to its 1200 W rating and the receiver combines passes. The 10 percent frame-error threshold is −0.6 dB-Hz for Variant A and −1.7 dB-Hz for Variant B (section 2.4). Against the single-pass figures above, the passes that must be combined are:

23 cm power	Single pass, albedo 0.152 / 0.117	Variant B, passes to combine	Margin after 5 passes (+7 dB)
1500 W	−3.3 / −4.4 dB-Hz	2 (+3.0 dB)	+5.4 / +4.3 dB
1200 W (rated)	**−4.2 / −5.4 dB-Hz**	**2 to 3 (+3.0 to +4.8 dB)**	**+4.5 / +3.3 dB**
1000 W	−5.0 / −6.2 dB-Hz	3 (+4.8 dB)	+3.7 / +2.5 dB
500 W	−8.0 / −9.2 dB-Hz	5 (+7.0 dB), no margin / does not close	+0.7 / −0.5 dB

Rayleigh fading (about 1 dB), pointing (0.7 dB two-way), and solar noise at 6° come out of those margins, and the model's 1.5 dB conservatism goes back in. At the amplifier's 1200 W rating the message closes on the second or third pass and keeps 3 to 4.5 dB after all five, which is what fading, pointing, and the Sun consume; at 1000 W it works with the full window; at 500 W it depends on luck. A single European receiver with the schedule file removes the question for that session.

The 2028 apparition. The next inferior conjunction is 2028-06-01 at 0.288 AU (43.2 million km, round trip 288 s), 6 percent farther than 2026 (−0.5 dB), and on that day Venus passes only 1.1° from the Sun, too close to point at. A week either side the separation is 10 to 12° at 0.295 to 0.297 AU (44.5 million km, −0.8 dB relative to 2026); two weeks either side it is 20° at 0.32 AU (−1.4 dB). Venus stands high at Haswell, 72 to 78° at transit and above 20° for about ten hours a day, which helps Tsys. So 2028 is not an easier target: it is

farther and nearer the Sun. What changes is the 13 cm package: at 2304 MHz with 1500 W the monostatic single pass is −1.1 dB-Hz (Variant A threshold −0.6), one combined pass short of closing, and Effelsberg receiving would sit at +13.9 dB-Hz. Whatever is learned at 23 cm in 2026 (real Tsys, real amplifier power, real pointing loss) is the input that makes the 2028 numbers trustworthy.

ORI's analytic check of the waveform gives a frame error rate of 2 percent at 0 dB-Hz, 38 percent at −1 dB-Hz, and 60 percent at −1.33 dB-Hz (AWGN); Pete's MATLAB channel adds Rayleigh fading with a 1.05 dB correction, and the DSES receiver validation (section 5.4) includes that so the margin is stated honestly.

2.3 Stations and frequencies

Station	Role in October 2026	Frequency
DSES Haswell, 18.3 m	Transmit and receive (this document)	**1299.5 MHz in 2026** with the 23 cm package: the B210 generates 1299.5 MHz directly, the package's transverter (1296 to 1298 MHz only) is bypassed, the 1200 W SSPA covers 1280 to 1300 MHz, and the feed retunes (Alex Nersesian, 2026-09-10; section 7.1). 13 cm package (2304 or 2400 MHz) not before the next apparition
Dwingeloo (CAMRAS), 25 m, 1000 W	Transmit and receive, own campaign	1299.5 MHz only (confirmed by ORI 2026-09-09)
Effelsberg, 100 m	Receive only, opportunistic, secondary to a baseline survey	Follows Dwingeloo; proposal alternates 1299.5 and 2304 MHz
Stockert, 25 m	Receive, own campaign	1299.5 MHz

Because DSES will be on 1299.5 MHz, the European stations can in principle receive DSES during the mutual window, roughly 13:30 to 16:30 UTC at low elevation on both ends (estimate, to be computed exactly when a session is arranged); the schedule file of section 8.1 is what makes that possible. Monostatic remains the baseline because it is the only mode DSES controls end to end.

2.4 Band plan and frequency dependence

The B210 tunes 70 MHz to 6 GHz, and the modem carries the dial frequency in the schedule, so the same software serves every band. What changes with frequency is computed per schedule from the ephemeris; what does not change is the waveform itself, which ORI defines with the same parameters on every band (their own smoke-test file is at 1296 MHz).

Band	Use	Two-way Doppler, Venus at conjunction	Peak rate, per symbol	Doppler spread (ORI: 1.5 Hz at 1299.5, scaled)
1296 MHz	EME tests, 23 cm package native	n/a (Moon: about ±2 kHz)	Moon: small	libration, variable
1299.5 MHz	**Venus 2026**; Dwingeloo, Stockert, Effelsberg band	+5.3 to −2.5 kHz	0.27 Hz/s, 45 Hz (8 spacings)	1.5 Hz
2304 MHz	13 cm package, next apparition	+9.5 to −4.5 kHz	0.48 Hz/s, 79 Hz (14 spacings)	2.66 Hz
2400 MHz	13 cm alternative	+9.9 to −4.7 kHz	0.50 Hz/s, 83 Hz (14 spacings)	2.77 Hz

The ORI waveform's 2.87 Hz bin is matched to the Doppler spread at 2304 MHz. At 1299.5 MHz the spread is 1.5 Hz, so a 2.87 Hz bin is wider than the channel needs and every frame carries almost twice the noise it has to. DSES therefore defines a second parameter set,

Variant B, for its own monostatic 23 cm operation: bins of 1.5 Hz, tone spacing 3.0 Hz, 247 frames per symbol so the symbol length (164.7 s), the message length, and the whole chunk schedule are unchanged. Everything else, the alphabet, the FEC, the payload, the bit mapping, the IF offset, is identical to Variant A. Figure 2 shows what it buys under ORI's own AWGN receiver model: the 10 percent frame-error threshold moves from about −0.6 dB-Hz to about −1.7 dB-Hz, 1.1 dB. Doubling the symbol to 473 frames (315 s) would reach −2.8 dB-Hz, but it halves the passes per session and so loses more in repeat-and-combine than it gains; it is kept as a schedule option only.

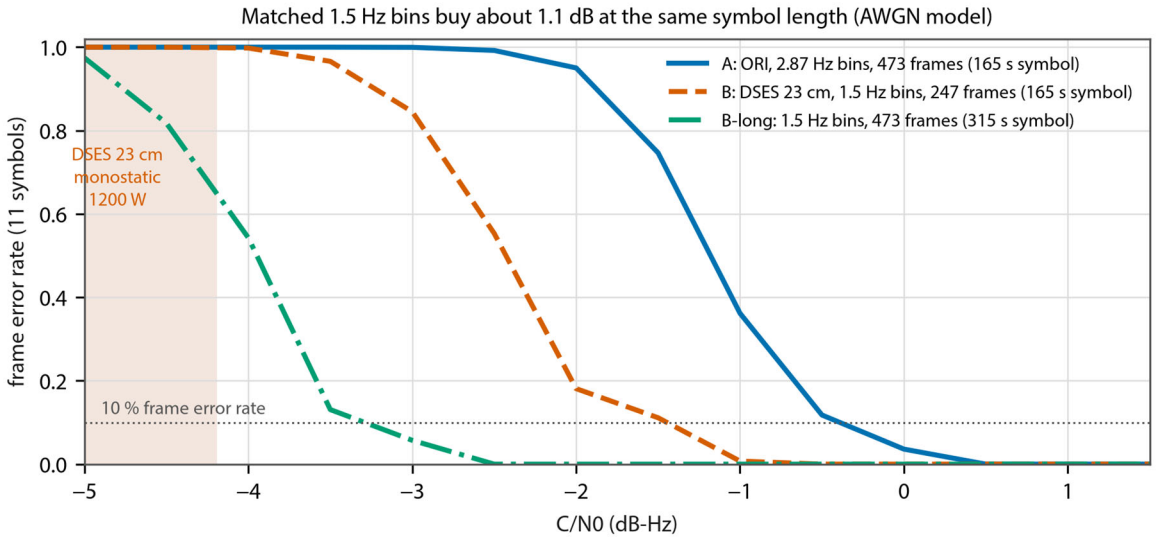


Figure 2 — Frame error rate versus C/N0 for ORI's Variant A and the DSES 23 cm Variant B, AWGN chi-square model with 4096 tones and 11 symbols. The shaded band is the DSES 23 cm monostatic link at 1200 W, from the date-resolved to the static albedo (−5.4 to −4.2 dB-Hz).

Variant B is a different signal on the air: a European receiver built to ORI's numbers will not decode it. It is therefore used only when DSES is its own receiver; any session with a partner receiver runs Variant A, and the schedule file names the variant (section 8.1). ORI is being told (O11). The RF package, feed, and amplifier per band are station items (section 7).

3. Architecture

3.1 The question: pre-generate or stream

ORI's implementation generates the complete waveform as a SigMF file and plays it through a B210 with GNU Radio. For a 30-minute message at 250 kS/s that is a 3.6 GB file, valid for one message and one Doppler profile. DSES will not operate that way, for four reasons:

1. **The station transmits in chunks with gaps** (section 4). A pre-generated file has no gaps; cutting it at run time is the same work as generating it at run time.
2. **Doppler pre-compensation changes continuously** and depends on the date, time, and target. A file generated for one session is wrong for the next.
3. **The waveform is trivial to synthesize**: one complex exponential at a time. At the radio's 1.5 MS/s that is a few million complex multiplies per second, well inside a Python NumPy budget, with no resampling because the tone is generated directly at the radio rate.
4. **Nothing is lost.** The transmit log records the schedule and the symbols, which together are a complete description of what went out; the IQ can be regenerated exactly.

The decision is therefore **stream**. The SigMF path is kept as an export (write ORI-format files for other stations and for the bench) and as an import (play an ORI file through the same transmit chain for cross-checks).

3.2 System block diagram

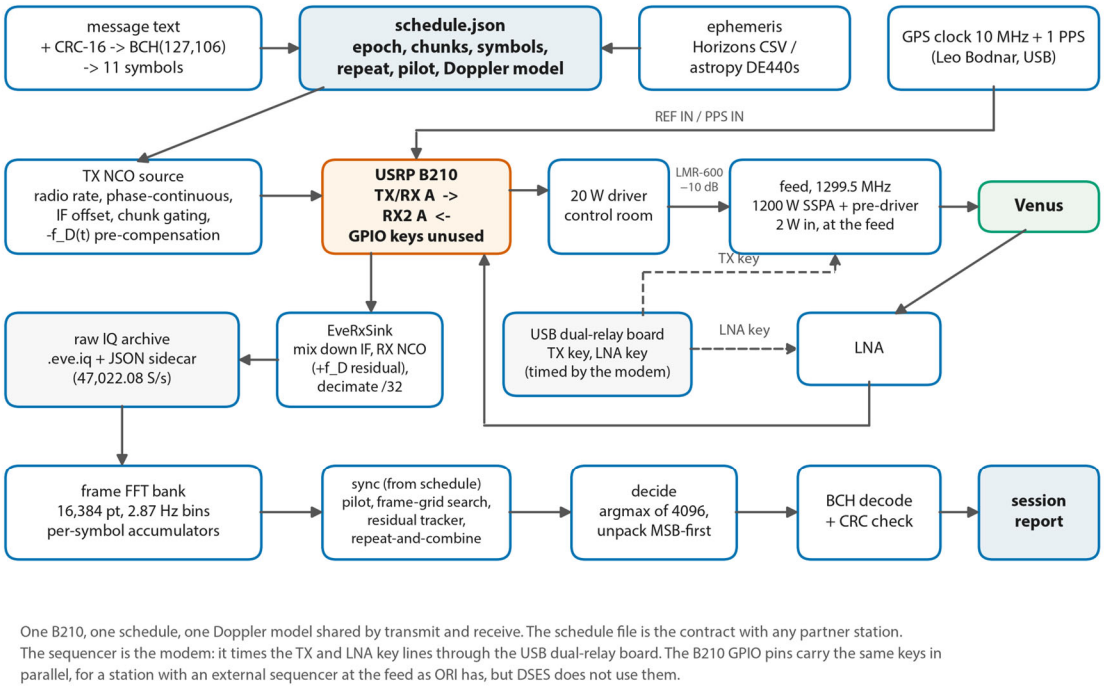


Figure 3 — System block diagram. Transmit and receive chains on one B210, both driven by the schedule file and the same Doppler model; the TX and LNA key lines come from the USB relay board, sequenced by the modem (the B210 GPIO pins carry the same keys in parallel and are unused at DSES).

The transmitter and receiver share one B210, one schedule, and one Doppler model. The schedule is the contract between them and, in bistatic operation, between DSES and the partner station.

3.3 Modes

Mode	Transmit	Receive	Schedule
Monostatic (baseline)	DSES, chunked	DSES, own echo, between chunks	Chunk length ≤ round trip; receive window = chunk + round trip
Bistatic transmit	DSES, message repeated; chunked only by the amplifier's duty limits (no echo wait)	Partner station	Chunks of T_on with T_off gaps, repeat count N; partner receives the schedule file. Continuous only if the amplifier can run the full 30 minutes
Bistatic receive	Partner	DSES	DSES receives the partner's schedule file
EME test	DSES, chunks of ≤ 2.5 s (Moon round trip)	DSES	Same machinery, `target=moon`, shorter symbol
Bench	B210 internal leakage, no PA	B210	Loopback, noise added offline

4. Operating concept

4.1 The message and its timing

One message is one BCH codeword: 106 payload bits (90 message bits plus a 16-bit CRC), encoded to 127 bits, carried in 11 symbols of 12 bits each (132 bit positions, the last 5 zero). Each symbol is one tone held for 473 frames of 1/2.87 s. The numbers:

Quantity	Value	Derivation
Frame (FFT block)	0.34843 s	1 / 2.87 Hz
Symbol	164.808 s	473 frames
Message (11 symbols)	1812.9 s = 30.2 min	11 × 164.808 s
Payload rate	0.058 bit/s	106 / 1812.9
Message text	11 ASCII characters (90 bits, 8-bit packed): **K0PRT K0PRT**	Schedule parameter

The message text is not written into code. It is a field of the schedule file (section 8.1, `message.text`) or the session tool's `--message` option; `message.py` only packs it. The DSES message is the station callsign repeated, **K0PRT K0PRT**, which is 11 characters and fills the 90-bit field exactly (a 12th character would be truncated). Appendix C gives the payload, the codeword, and the 11 symbols for that text, computed with ORI's own generator, as the project's reference test vector.

The frame is the unit everything is scheduled in. Frame k is the k-th frame the session transmits: it carries symbol floor(k / 473) mod 11 of message repetition floor(k / 5203), and frames are counted only while the transmitter is on, so the off periods between chunks do not consume frames. The schedule's chunk table (section 8.1) maps each frame range to its UTC transmit time; within a chunk, frames follow one another every 1/2.87 s. A receiver files every frame it receives into the accumulator of the symbol that frame belongs to. Because detection is non-coherent, frames of one symbol need not be contiguous in time, which is what makes chunking possible.

4.2 Monostatic chunking

DSES listens to its own echo, so the transmitter must be silent when the echo arrives. With round-trip time RTT, a chunk of length T_on transmitted from t = 0 returns during [RTT, RTT + T_on]. The next chunk may start at RTT + T_on. The DSES amplifiers add a duty limit of about 5 minutes on and 4 minutes off. The constraints are therefore T_on ≤ min(RTT, 300 s) and T_off ≥ max(RTT, 240 s), and the cycle is T_on + T_off.

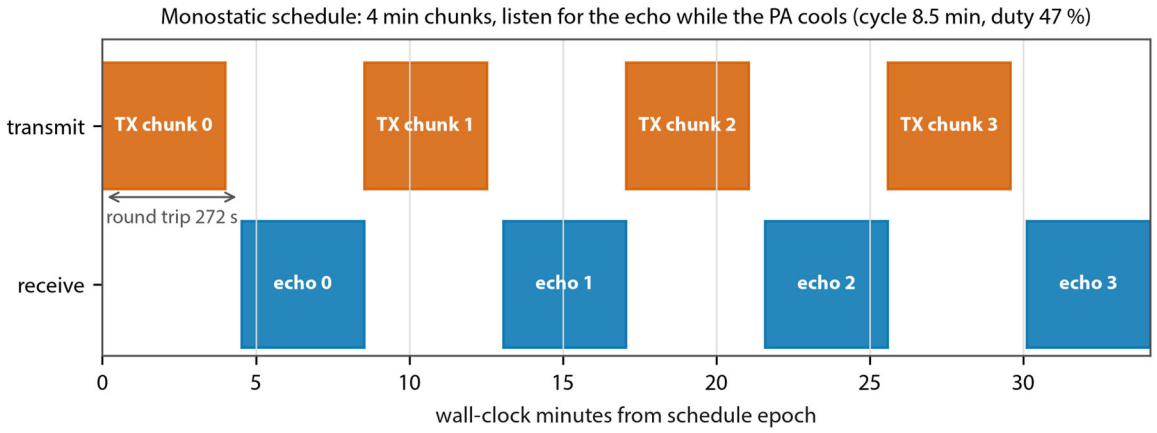


Figure 4 — Monostatic schedule with 4-minute chunks. Each chunk's echo returns 272 s after it was sent and is received while the amplifier cools; the next chunk follows the echo.

Shorter chunks are kinder to the transmitter but cost wall-clock time, because every chunk pays the full round trip in silence:

Chunk T_on	Cycle	Duty	Chunks per message	Wall-clock per message
1 min	5.5 min	18 %	31	167 min
2 min	6.5 min	31 %	16	100 min
3 min	7.5 min	40 %	11	78 min
4 min	**8.5 min**	**47 %**	**8**	**64 min**
4.5 min (= RTT)	9.0 min	50 %	7	59 min

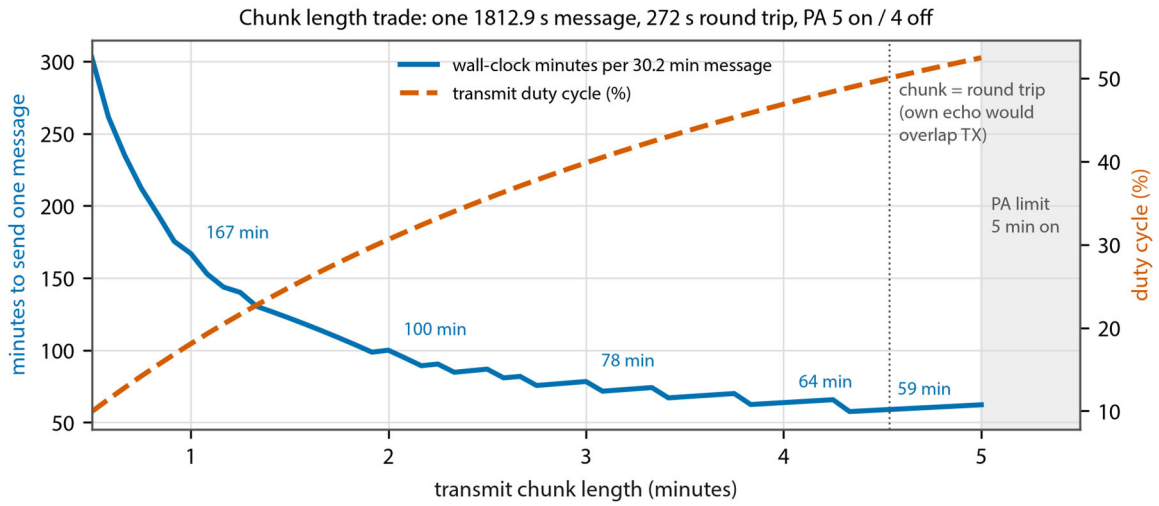


Figure 5 — Wall-clock time to send one 30.2-minute message and transmit duty cycle as a function of chunk length, for a 272 s round trip and the 5-on/4-off amplifier limit.

The working value is **4 minutes**: it keeps a 30-second guard below the round trip so a chunk's own echo never overlaps the next transmission, stays a minute under the amplifier's 5-minute limit, and delivers a message in 64 minutes. On conjunction day the 5.75-hour window above 20° elevation holds five message passes, which is what repeat-and-combine needs. Chunk boundaries fall on frame boundaries; a symbol may straddle a gap.

Symbol boundaries and chunk boundaries are independent. The alternative of making each chunk exactly one symbol (a 165 s chunk, 2.7 min) is a valid setting of the same parameter and is listed for completeness; it buys nothing the receiver needs and costs 20 percent in wall-clock time relative to 4-minute chunks.

Bounding the run (D26). The chunk table is laid from the start time until the repeat count is satisfied, but never past a stop time: the earlier of an operator-set UTC stop and the moment the target drops below the minimum elevation (10° by default, the operating schedule's floor). No chunk is planned whose echo would arrive after the stop, so the schedule file is the whole run and the report states how many passes were complete. The start may likewise be "when the target rises" above that elevation, so the operator can press START hours ahead and the modem waits with the radio open; the day's window, the chosen start and stop and the passes that fit are printed at the head of the schedule preview, and `ops.py` produces the same arithmetic for a span of days (the operating schedule table). A run in progress can also be ended cleanly at a chunk boundary: the chunk being transmitted completes and its echo is received, no further chunk is keyed, and the decode and report follow with the passes in hand. The abort remains the immediate path (key released at once).

4.3 Time and frequency reference

Pete's design assumes stations sharing a hydrogen maser over White Rabbit. The DSES receiver is non-coherent, so it needs two things only: to know which frame is which, and to have the tone land within a fraction of a 2.87 Hz bin for the whole symbol.

- **Time.** A GPS-disciplined 10 MHz and 1 PPS go into the B210's REF IN and PPS IN. The modem sets the USRP time to UTC on a PPS edge, so every transmitted sample and every received sample carries a UTC timestamp good to well under a millisecond. The schedule epoch is a UTC instant; within a chunk, frame boundaries are the chunk's start + j × 0.34843 s. The receiver maps arrival time to frame number through the ephemeris round-trip time. The tolerance is about one frame: every frame of a symbol carries the same tone, so a one-frame grid error costs 1/473 of the symbol's energy (verified in simulation, section 5.4), and GPS provides microseconds. The station reference is a Leo Bodnar Precision GPS Reference Clock (D23): its output 1 gives the 10 MHz, and its output 2, left disabled, carries the receiver's 1 PPS. Should a session ever run without a PPS, the modem sets the USRP time from the host's NTP clock instead (host-timed mode); that is good to tens of milliseconds against the one-frame tolerance, so it is a fallback, not a degradation of the decode.
- **Frequency.** The same GPSDO disciplines the B210's master clock. A B210 on its internal TCXO is ±2 ppm, or ±4.6 kHz at 2304 MHz with drift of tens of hertz per session; that alone would defeat a 2.87 Hz receiver. Locked to a GPSDO the reference is 1e-11 or better, 0.02 Hz at 2304 MHz.
- **Ephemeris.** Round-trip time and Doppler come from a JPL Horizons table (topocentric, one row per second, fetched before the session and stored with the schedule), with astropy plus a local DE440s file as the offline fallback. The two are cross-checked before every session.

4.4 Doppler

The two-way Doppler at 2304 MHz on conjunction day sweeps from +9.5 kHz to −4.5 kHz across the pass and its rate peaks at −0.48 Hz/s (Figure 1). Across one 165-second symbol that is 79 Hz, 14 tone spacings; across one 0.35-second frame it is 0.17 Hz, six percent of a bin. So the frame is short enough that a tone stays put within a frame, and the symbol is long enough that the tone must be steered.

The modem does both halves:

- **Transmit pre-compensation.** The transmit NCO is offset by −f_D(t) for the designated receiver's geometry, so the echo arrives at the nominal comb. For monostatic operation that is the Haswell two-way Doppler at the echo's arrival time, t + RTT. For bistatic operation it is the uplink Doppler at Haswell plus the downlink Doppler at the partner (the schedule file names the receiver so both ends agree on who compensates what).

- **Receive residual tracking.** The receive NCO applies the same model from the receiver's side, and a slow tracker corrects the residual from the model's error and the reference's drift using the energy of the detected tone. Frames are then on the design grid.

The Doppler model is a first-class part of the schedule file so that an offline receiver at another station can apply exactly what the transmitter assumed.

4.5 Repeat-and-combine and the pilot

Because the message is repeated within a session, the receiver keeps accumulators per symbol across repetitions. Deciding on the sum over N repetitions is equivalent to N times the frames per symbol, worth 10 log10 N dB of sensitivity: two passes buy 3 dB, five buy 7 dB. The ORI README suggests exactly this; here it is designed in from the start and the schedule file carries the repeat count.

An optional **pilot** reserves a known tone for the first 40 frames (14 s) of each chunk. It costs 6 percent of throughput and lets the receiver check the frequency model and the signal's presence live, at the start of each chunk. What it can and cannot do follows from the waveform: a tone that is constant for 40 frames carries timing information only at its two edges, so the pilot measures the frequency offset well (to R_bw / 8 by summing the frames' power in a zero-padded FFT) and confirms presence, but at the 0 dB-Hz design point 40 frames give only about a 2-sigma presence detection and a 1-sigma decision between adjacent whole-frame epochs. Timing of record is therefore GPS plus the ephemeris (section 4.3); the pilot is a live sanity check at Venus and a decisive one at EME strength. The pilot is on for the EME test and for the first Venus sessions; it is a schedule flag, not a waveform change. Its length is an operator setting per chunk (application 1.0.10): the 40 frames above suit the 240 s Venus chunk, but a monostatic Moon chunk of 2.4 s holds six Variant A frames, so there the pilot is at most four and the EME defaults use two, each pilot frame displacing a data frame; the application caps the setting to the chunk and the worker refuses a schedule whose chunks cannot hold pilot + 2.

4.6 The EME proof test

Everything above is exercised against the Moon before Venus, at very low power. What changes is parameterized, not rewritten:

Parameter	Venus	Moon
Round-trip time	272 s	2.5 s
Chunk length (monostatic)	≤ 272 s, working 240 s	≤ 2.5 s (7 frames), alternating TX and RX
Two-way Doppler	±10 kHz, rate ≤ 0.5 Hz/s	±4 kHz at 1296 MHz, rate small
Spread	2.87 Hz assumed	Libration spread at 1296 MHz can exceed 5.74 Hz; pick a low-libration window or set R_bw from the predicted spread
Link	C/N0 −4 to +2 dB-Hz by band and power	B210 output alone (+10 dBm) gives +12 dB-Hz at 1296 or 1299.5 MHz and +16 dB-Hz at 2304 or 2400 MHz (Tsys 60 / 76 K, mean Moon distance); 0 dBm gives +2 and +6
Frequency	1299.5 MHz (2026)	1296 or 1299.5 MHz and 2304 or 2400 MHz: both bands, no amplifier needed

The B210 alone is the transmitter for EME testing. Its +10 dBm output through the feed lands 12 to 16 dB above the design point, so the test is run at the design point by turning the B210 output down, or by adding calibrated noise to the archive offline, with no amplifier in the chain, on either band, as soon as a feed and a transmit/receive switch at the feed exist (O12). This decouples validation of the modulation and protocol from the amplifier schedules entirely, which is why it can start before the 23 cm driver and sequencer exist and long before the 13 cm package.

The EME test proves the schedule and keying at the fastest cadence the design will ever use, the GPS timing, the Doppler module with a different target, the receiver, and repeat-and-combine, end to end. Its switching rate (2.5 s alternation) is a station question recorded in section 10.

5. Software design

5.1 Module layout

The modem is a Python package `eve/` in this project, pure NumPy/SciPy in the core with GNU Radio only in the two blocks that touch the radio:

Module	Responsibility
`params.py`	`EveParams`: R_bw, N_fft, M, N_frames, N_sym, BCH n/k, IF offset, radio decimation, with the Python-Implementation values as defaults and the MATLAB set selectable for reproducing Pete's curve. Derived quantities (modem rate, frame, symbol, message time).
`bch.py`	BCH(127,106), t = 3, narrow-sense systematic, generator polynomial octal 11554743 over GF(2^7) with primitive x^7+x^3+1. Encoder and Berlekamp-Massey / Chien decoder. Verified against `galois` and against the Lin & Costello table.
`message.py`	Text ↔ 90 bits (8-bit ASCII, zero-padded); CRC-16-CCITT (0x1021, init 0xFFFF); payload assembly; verification on decode. The text itself comes from the schedule.
`modem.py`	Symbol packing (MSB first, 132 positions), tone map, the streaming synthesizer (phase-continuous, chunk-gated, Doppler-offset NCO at any sample rate), and the receiver core: frame FFT bank, per-symbol magnitude accumulators, decisions, unpacking. Faithful to the ORI conventions; no Doppler or sync inside.
`channel.py`	Pete's `channel.m` (AWGN + random phase + Rayleigh, −1.05 dB) plus a streaming extension with Doppler ramp, timing offset, and gaps.
`montecarlo.py`	Success-rate vs C/N0 and vs frames-per-symbol curves; the Rayleigh version of ORI's link check.
`doppler.py`	Two-way topocentric Doppler and round-trip time vs UTC for target `venus` or `moon`, from a Horizons table (primary) or astropy + DE440s (fallback); visibility window.
`schedule.py`	The block-slot timeline: epoch, chunks, receive windows, frame-to-symbol map, repeat count, pilot flag; JSON in and out (section 8.1).
`ops.py`	Operations planning (4.2, D26): the target's windows above a minimum elevation from the ephemeris table, the start ("when the target rises") and stop (UTC stop or the window's end, whichever is first) a run is bounded by, the operations header of the schedule preview, and the day-by-day operating schedule table (passes that fit, last echo, range and loss against the best day).
`sync.py`	Pilot detection, frame-grid search (±N frames), residual frequency tracker, repeat-and-combine. Everything the reference design does not have, kept out of `modem.py`.
`sigmf_io.py`	Export in ORI's SigMF form (`ori:design` block) plus a `dses:` block; import of ORI files for playback.
`gr_blocks.py`	`EveToneSource` (schedule-driven NCO source at the radio rate) and `EveRxSink` (decimate to the modem rate, archive IQ, feed the live accumulators).

Module	Responsibility
`radio.py`	B210 setup: external reference and PPS, `ref_locked` readback, UTC time set on PPS (or from the host clock when no PPS is present), IF-offset tune with readback verification, rate readback, GPIO keying line. Factored from the Workbench (section 9).
`gpsdo.py`	The Leo Bodnar GPS reference clock over USB HID: status (satellite and PLL lock, signal-loss count), configuration read-back, divider planning, and the preflight that programs the station setting of section 7.1 and waits for lock before the radio opens.
`station.py`	Key-down and cooldown interlocks, PA duty enforcement, abort, session log; one flowgraph per session; a simulated radio (delay line plus AWGN) for the software bench.
`display.py`	Operator display (PySide6 and pyqtgraph): tone strip, accumulated metric of the current symbol, running decisions with margins, chunk and keying state, radio status, ephemeris, abort. `OperatorPanel` is re-bound to each session; `OperatorWindow` wraps it for the command-line tools.
`decode.py`	The offline decode of an archive (the decision of record) and its summary, shared by the tools and the application.
`report.py`	The session report PDF (8.4): verdict, decisions with margins per pass, timeline, per-window synchronization, key events.
`siggen.py`	The signal generator (5.8, D25): a schedule of on-windows for a requested duration, a CW / two-tone / EVE-waveform source gated by it, a live level control (B210 TX gain and a digital scale), a timed gain sweep, and a one-page report of every level step and key event.
`worker.py`	The run in its own process (radio, GPS clock, ephemeris, schedule, session, decode, report), talking to the application over a pipe. A fresh UHD per run: a second USRP source in one process crashed, and the constructor faults intermittently on Windows, so the application retries the open and survives a worker crash.
`app.py`	The application (`eve_app.py`, desktop icon): one window for simulation, bench, EME and Venus runs with remembered settings (INI), the operator panel, and the report viewer; every control carries operator help. Runs repeat without restarting the program.
`_workbench.py`	Finds the Workbench clone and imports its shared `dses_radio.py` (section 9).
`tools/`	`eve_session.py` (plan a session from Horizons, run a schedule on the radio, or simulate it), `eve_decode.py` (offline decode of an archive, the decision of record), `eve_bench.py` (B210 loopback), `eve_txcw.py` (one comb tone into the lab counter: the transmit-frequency check of 5.4); `--gpsdo` on these commands adds the clock preflight. The application (`eve_app.py`) does all of this from the window; the tools stay for scripts and the field log.

5.2 Transmit path

`EveToneSource` produces samples at the radio rate directly: for sample n at time t_n it outputs A × exp(j × 2π × (f_IF + d(k) × Δf − f_D(t_n)) × t_n + φ), with d(k) the symbol of frame k, and φ carried across symbol hops so phase is continuous. Outside an on-window it outputs zeros and the keying line is released. The block never touches a file; the schedule is its only input. Buffering follows the Workbench's proven practice for the B210 transmit edge (deep minimum output buffer, real-time mode during a chunk) so a 4-minute chunk runs without underruns; underruns are counted and logged.

The B210 TX/RX A port drives the amplifier chain; RX2 A takes the LNA. The two ports are always so assigned; the modem refuses to start if the receive port is on TX/RX.

5.3 Receive path

A two-stage front end takes the B210 stream (radio rate = 32 × modem rate, nominal 1.5047 MS/s) to the modem rate: a frequency-translating complex band-pass filter mixes the comb down by the IF offset (plus the bulk Doppler when this receiver is not the pre-compensated one, stepped once a second from the model) and decimates by 16, then a sharp low-pass at the intermediate rate decimates by 2. Two stages because the comb fills the modem-rate Nyquist band exactly (M × 2 R_bw = N_fft × R_bw by construction): the second stage is flat to 99.5 percent of the bandwidth with its transition centered on Nyquist, so only the last few tones sit in the transition band and take alias noise. A single-stage design cut the top tones by 8 dB. `EveRxSink` then writes the stream to the session archive as complex64 with a JSON sidecar (section 8.2), one file per receive window, time-stamped from the radio's `rx_time` tags and zero-padded across overflows so the sample clock stays honest. At 376 kB/s a full 6-hour window is 8 GB; the archive is always written so any session can be re-decoded offline with a different schedule, Doppler model, or receiver. In parallel the live receiver runs the 16,384-point frame FFT bank, files frame magnitudes into the symbol accumulators, and shows the running symbol decisions and the tone-strip display.

The decoder is deliberately offline-first: the live view is for the operator; the decision of record is the offline decode of the archive after the session.

5.4 Validation plan

Stage	What	Gate	Status 2026-09-12
0	Reference vectors: ORI generator output for a fixed message; BCH round trip against `galois`	Bit-exact symbols and codeword	Passed: Appendix C bit-exact; BCH matches `galois` on encode and on up to three errors
1	Modulator: DSES streaming synthesizer vs ORI file for the same message, same rate	Tones and phase match to float tolerance	Passed: phase constant within every symbol against ORI's equation; ORI's own smoke file read back
2	Receiver in simulation: Pete's channel (Rayleigh) and ORI's AWGN model; frames-per-symbol sweep	Reproduces both curves; Rayleigh margin stated	Passed: Variant A reproduces ORI's table; Variant B +1.1 dB
3	Streaming realism: Doppler ramp, chunk gaps, wrong epoch; real CAMRAS Venus echoes (March 2025, public) through the FFT bank	Decodes at the design point with a 0.5 Hz/s ramp; pilot recovers a wrong epoch	In part: 0.48 Hz/s ramp pre-compensated and receiver-removed, gaps, one-frame epoch error, four-pass combining all decode in simulation; CAMRAS echoes not yet run

Stage	What	Gate	Status 2026-09-12
4	B210 loopback on the bench: 4-minute chunk soak, underruns, reference lock, rate readback, transmit frequency vs the lab GPS reference on the E4438C / 53230A	Zero underruns, frequency within 0.1 Hz	In part (2026-09-11): 22 chunks at minimum TX gain, both passes decoded at about 25 dB margin, no underruns, rate read back 0.3 ppm off nominal. 2026-09-12, on the GPS clock's 10 MHz and 1 PPS: `ref_locked` true, USRP time set on a PPS edge (set error 0.000000 s), both passes decoded at 24 to 26 dB margin; transmit frequency against the lab reference on the 53230A: −0.03 Hz mean at 1,296,025,000 Hz (10 s gate, six readings, 0.012 Hz rms; −0.06 Hz at 1 s gate). Passed; O16 closed
5	EME at very low power	End-to-end decode at C/N0 near 0 dB with the station's own keying	Not started
6	Venus, sessions from mid October		

5.5 Receiver algorithms

For a reviewer who wants to check the receiver against the design rather than take it on trust, this is what `modem.py`, `sync.py` and `decode.py` do, in the order the samples see it. Names are the ones in the code.

Frame metric (`FrameBank.frame_metric`). Each frame of N_fft = 16,384 baseband samples at the modem rate is windowed, transformed, and reduced to the M = 4096 candidate-tone magnitudes (tone d at FFT bin

2d, the ORI placement). The metric of a frame is that 4096-vector; nothing coherent survives a frame boundary, by design (section 4.1).

Symbol accumulation (`SymbolAccumulator`). Frame k maps to (repetition r, symbol m, frame-within-symbol) through the schedule's frame map (`FrameMap`), pilot frames excluded. The accumulator adds frame metrics per (r, m); `combined()` sums the repetitions the operator asks for (all of them by default), `decide()` takes the arg-max tone per symbol, `margin_db()` is the dB gap between the winning tone and the runner-up, and `decode()` unpacks the 11 symbols to 132 bits (MSB first), runs the BCH(127,106) decoder with t = 3 (`bch.py`), checks the CRC-16 (`message.py`) and returns a `DecodeOutcome` whose `ok` is true only when the CRC matches. The Monte Carlo in `montecarlo.py` reproduces ORI's frame error table with exactly this chain (section 5.4, stage 2), which is the evidence that the accumulation is the non-coherent sum Pete's design assumes.

Pilot (`PilotDetector`). A window's first `pilot_frames` frames carry a known tone (section 4.5). `presence()` sums those frames' metrics and reports the contrast of the expected tone against the median of the others; `frequency()` zooms an R_bw/8 spectrum around it for the frequency offset; `search()` slides the frame grid over ±N frames and takes the offset with the best contrast, returning a `SyncEstimate` (frame shift, frequency offset, contrast, detected flag). At EME strength this is a solid detection; at the Venus design point it is a 2-sigma presence check and the timing of record is GPS plus the ephemeris, as section 4.5 says.

Epoch without a pilot (`decode._epoch_shift`, `sync.grid_search`). ORI's generator sends no pilot, so a receive-only interop run finds the frame epoch by matching the known symbols of the schedule over ±N frames on the first window; the shift that maximizes the accumulated metric wins. Verified on synthetic offsets of 0, +4, −3 and +9 frames.

Frequency tracking (`FrequencyTracker`). Per-frame decisions are useless at Venus SNR, so the tracker accumulates an exact zoomed spectrum (R_bw/8) around the tone the schedule says is being sent, over blocks of frames, and reports the residual offset; the receive chain's shift follows it. On the bench the residual is zero to two decimals; on the air it is what remains after the transmit pre-compensation (section 4.4).

Window processing (`WindowReceiver.process`). One receive window at a time: optional pilot search, optional tracking, frame metrics into the accumulator, a `WindowResult` with the sync estimate and the residual. `decode_archive()` walks the archive's windows in schedule order, pads a window that ends within a tenth of a frame short (the B210 delivers 49,151 samples where 49,152 were asked, section 8.2), applies the epoch search where there is no pilot, merges accumulators across windows (`merge_accumulators`) and returns the decision of record with `summarize()` for the report (section 8.4).

Thresholds. The design 2.4 chi-square model gives, for a one-pass decode at 10 percent message error, −0.6 dB-Hz at 473 frames for Variant A and +11.7 dB-Hz at the 6-frame bench length; the application quotes the threshold for whatever length is set (`cn0_threshold_db`, a 6.5 dB-per-decade fit to the model within 0.7 dB).

5.6 Process architecture and fault handling

One run, one process. Every session runs in a worker process spawned by the application (`worker.py`, `multiprocessing` spawn context) with a fresh UHD; the two talk over a pipe with typed messages: `log`, `state` (phase text), `preview` (the schedule description), `session` (the schedule and radio facts for the display), `frame` (a frame's metric for the live view), `status` (phase, key and radio text every half second), `notice` (something the operator must see but that must not stop a timed run), and the final result. The reason is a fault in UHD 4.10 on Windows: `usrp_source`'s constructor dies with an access violation in about one open in five when a device is reopened, and a second source in one process faulted every time. The controller retries a worker that dies before the session exists up to three times; the window survives a worker crash and says so. Scripts that spawn workers carry the `if __name__ == "__main__"` guard the spawn context needs.

Before any RF. The worker opens the radio, then the GPS clock preflight (the HID handle is closed before UHD enumerates, section 7.1), then configures the radio and refuses to continue without reference lock on the air; it opens the key line and puts every output in the receive state; it builds the schedule and runs the session preflight (chunk lengths against the amplifier limits, the sequencer's needed gap, the ephemeris model where the options require one). Any failure ends the run here with the reason in the log and on screen.

During the run. The keyer thread keys T_lead plus the sequencer's settle time before each chunk's RF and releases T_lag after; a watchdog releases the transmitter if a chunk overruns the amplifier limit; a keying fault (a relay board that stops answering) is logged and shown in the key lamp text, and the run continues under the operator's eye rather than being killed mid-chunk. Abort, from the button or the watchdog, releases the transmitter first, then the LNA, stops the streams, and closes the archive so what was received is still decodable. Receive overflows are measured and zero-padded so the sample clock stays honest (section 8.2).

After the run. The offline decode runs on the archive, the report PDF is written (section 8.4), the radio is closed with its blocks released and garbage-collected, and the worker exits. Faults in the decode or the report are logged and do not lose the archive.

After an underflow. The transmit stream is one timed burst: the first sample carries `tx_time`, and gr-uhd stamps every later packet from the sample count. When the host falls behind (a stalled or throttled CPU), every packet after the underflow carries a time already past, the radio drops each one as late, and nothing reaches the air again for the rest of the run; that is what ended the Haswell runs of 20 and 23 October 2026.

The tone source therefore watches the device clock (`EveToneSource`, three times a second): when the sample it is about to generate lies a quarter second behind the clock, it ends the burst (`tx_eob`), skips the backlog, and begins a new timed burst one second ahead (`tx_sob`, `tx_time`), which gr-uhd's burst handling re-arms the radio for. The frames in the skipped seconds are lost; the chunk in progress is named in the log and the session JSON (`tx_resyncs`), the count rides in the transmitter warning, and the run goes on. The clean stop and the stop time (D26) bound the run; the resync keeps it alive.

5.7 Test suite

`tests/` (62 tests, run with `python -m pytest tests -q` in the project environment) are the executable form of the validation plan:

File	Covers
`test_eve_core.py`	Stages 0 to 2: Appendix C symbols and codeword bit-exact against ORI's generator; BCH against `galois` on encode and on up to three errors; the DSES synthesizer against ORI's equation; loopback decode on Variants A, B and the MATLAB set; the channel's C/N0 calibration; the chi-square frame model against Pete's channel; streaming decode with timing offsets, gaps and Rayleigh fading
`test_eve_session.py`	Doppler and round trip from a Horizons table and from astropy; the schedule's chunking, frame map, JSON round trip and validation; pilot detection, grid search and the tracker on synthetic signals; SigMF export and import
`test_eve_station_sim.py`	A whole session on the simulated radio: chunks keyed, archive windows of full length, live and offline decode of both passes, amplifier-limit preflight; a clean stop during the second chunk (that chunk and its echo complete, no third chunk keyed, the stream ends after the echo, the archive decodes); the stream's resync after a 6 s stall of the device clock (one resync, the chunk that lost frames named, the run completes)
`test_eve_ops.py`	Operations planning on a fabricated ephemeris: windows, rise and set refined between rows, the highest point; the start and stop a run derives from them (UTC stop versus elevation stop); a schedule truncated at the window; the day table and its text
`test_eve_keyer.py`	Relay frames and checksums; the USB relay board against a fake port; the sequencer's order and states on both outputs; the GPIO-only fallback; board discovery
`test_eve_siggen.py`	The generator's schedule (on-time adds up to the duration, chunked under the amplifier limits), the source's tones and gating, the sweep's levels, and a whole generator session on the simulated radio with a sweep and the report
`test_eve_gpsdo.py`	The GPS clock's HID report decoding and the divider planner against the vendor's plan
`test_eve_display.py`	The operator panel renders headless and binds a session
`test_eve_app.py`	The application end to end, headless: settings, schedule preview, a simulated run through the worker process, the report rendered, a re-decode, a second run

5.8 Signal generator for the RF package

Integrating the transmit chain (the 20 W driver, the 1200 W SSPA at the feed, filters, and the feed, 7.1) needs a source that behaves like the modem, keys like the modem, and can be turned up and down while a power

meter or spectrum analyzer watches the output. Rather than a separate instrument on the bench, the modem has a **signal generator run mode** (`siggen.py`, `eve_app.py` mode "Signal generator"; operator's guide 4.6):

- **Signals.** CW at the dial frequency plus an offset; two equal tones at a set spacing (intermodulation and compression); or the EVE waveform itself with the pilot, exactly the session's transmission. The CW and two-tone sources are phase-continuous NCOs at the radio rate, gated by the schedule's on-windows like `EveToneSource`.
- **Operation and keying.** The generator is an instrument, not a schedule: it comes up with the key up and stays up until the operator stops it. KEY and UNKEY on the Run tab go through the sequencer (D24) with the session's key lead and lag, as often as the operator likes. With the amplifier in the chain the 7.2 limits apply per key-down (released at T_on,max, refused until T_off,min has passed); a watchdog releases the transmitter if the program stops ticking; Abort releases it first. Nothing is received or decoded. (The first 1.0.7 generator ran for a set duration; the operator's bench work showed that keying at will is what integration needs, 2026-09-23.)
- **Level and signal, live.** The B210 TX gain (0 to 89.75 dB in 0.25 dB steps, set on the device while streaming) is the coarse control and a digital multiplier before the sink (dB below full scale) the fine one; the signal kind, offset and spacing change the source at its next sample block. All apply immediately from the Setup tab, keyed or not, and every change is logged with its UTC time. A timed sweep steps the gain from a start to a stop level by a step, holding each for a set time, on the first key-down and on request, so a compression curve is one run against the meter's readings.
- **Dry run.** The same run on the simulated radio, with the USB relay board and the simulated GPIO lines: the station's wiring to the relays is checked with no RF at all.
- **Report.** One page: settings, every level step, every key event, with times, in the archive folder beside the schedule file.

Reading the power meter and the spectrum analyzer into the report (the lab's instruments are reachable over the network) is a planned extension (O18).

6. ICD part A — the air interface

This section is the interoperability specification. It follows the ORI Python implementation exactly where that implementation is definite, and it resolves, by definition, two places where it is not. Items marked TBC are awaiting confirmation from Pete Wyckoff and Michelle Thompson (asked 2026-09-09).

6.1 Waveform parameters

Parameter	Symbol	Value	Source and notes
Modulation		4096-ary orthogonal FSK, non-coherent	Pete Wyckoff, Spiral #2
FFT bin width = frame rate	R_bw	2.87 Hz	ORI Python; equals the Doppler-spread forecast at 2304 MHz, applied by ORI on every band. TBC: the MATLAB used 2.67 Hz; see O11 for 23 cm
Tone spacing	Δf	5.74 Hz (= 2 R_bw)	One guard bin between tones
Alphabet	M	4096 tones, 12 bits per symbol	
Frames per symbol	N_frames	473	ORI Python; its README notes Pete's slide shows about 440. TBC
Symbol duration	T_sym	164.808 s (= 473 / 2.87)	Defined as an integer number of frames. ORI Python uses 164.794 s (472.96 frames); the 14 ms difference is resolved here in favor of whole frames
Symbols per message	N_sym	11	
Message duration	T_msg	1812.9 s	
Occupied bandwidth		23.5 kHz (4096 × 5.74 Hz)	
FEC		BCH(127,106), t = 3, narrow-sense, systematic (message bits first)	Generator octal 11554743; identical in MATLAB and Python
Payload		90 message bits + CRC-16-CCITT (0x1021, init 0xFFFF, no reflection) over the 90 bits, MSB first	ORI Python
Message text		11 ASCII characters, 8 bits each, MSB first, zero-padded to 90 bits	90 bits = 11.25 characters; the 12th is truncated

Parameter	Symbol	Value	Source and notes
Bit-to-symbol map		127 coded bits zero-padded to 132; symbol m = bits 12m … 12m+11, first bit most significant	ORI Python. The MATLAB used LSB first
Amplitude	A	constant, 0.8 of full scale in ORI files	Constant envelope; Class-C amplifier compatible
Phase		continuous through a symbol; at symbol hops DSES keeps phase continuous (ORI files restart from a global index). Receiver-invisible	

6.1.1 Variant B — DSES 23 cm monostatic

Selected by `waveform.variant = "B"` in the schedule. Only the rows below differ from Variant A; a receiver that does not implement Variant B must refuse a Variant B schedule.

Parameter	Variant A (ORI)	Variant B (DSES 23 cm)	Note
Bin width = frame rate, R_bw	2.87 Hz	1.5 Hz	matched to the 1.5 Hz spread at 1299.5 MHz
Tone spacing, Δf	5.74 Hz	3.0 Hz	still one guard bin
Frame length	0.34843 s	0.66667 s	= coherence time at 23 cm
Frames per symbol, N_frames	473	247	symbol 164.67 s, message 1811.3 s: schedule unchanged
Occupied bandwidth	23.5 kHz	12.3 kHz	same 25 kHz IF offset
Modem sample rate, N_fft × R_bw	47,022.08 S/s (N_fft 16,384)	24,576 S/s (N_fft 16,384)	radio rate 32× = 786,432 S/s
Performance (AWGN model, 10 % FER)	−0.6 dB-Hz	−1.7 dB-Hz	+1.1 dB
Interoperable with ORI receivers	yes	**no**	DSES monostatic only

6.2 Tone map and spectral placement

Tone d (0 … 4095) is at baseband frequency f_d = d × Δf above the comb origin, one-sided, 0 to 23,505 Hz. The comb origin sits at an IF offset above the dial frequency so that tone 0 is not on the zero-IF spike:

f_RF(d) = f_dial + f_IF + d × Δf, with **f_IF = 25,000 Hz** and Δf = 5.74 Hz (Variant A) or 3.0 Hz (Variant B).

Published operating parameters are therefore two numbers: f_dial (the frequency the transmitter is tuned to) and f_IF (25 kHz unless a schedule says otherwise). The comb occupies f_dial + 25.0 kHz to f_dial + 48.5 kHz. A receiver tunes to f_dial, mixes down by f_IF plus the applicable Doppler, and sees tone d at d × 5.74 Hz. This is the ORI convention (their README: "tune the B210 25 kHz low"). The MATLAB placed the comb symmetrically about DC; that convention is not used on the air.

6.3 Receiver reference implementation

- Frame length 1 / R_bw (0.34843 s for Variant A, 0.66667 s for Variant B). The modem sample rate is defined as N_fft × R_bw with **N_fft = 16,384, giving 47,022.08 S/s (Variant A) or 24,576 S/s (Variant B)**, so a frame is exactly 16,384 samples and tone d is exactly FFT bin 2d in either variant. Any radio rate is bridged to this by resampling (DSES: 32 × modem rate at the B210, integer decimation).
- Per frame: FFT of the frame, magnitude at the 4096 candidate bins.
- Per symbol: sum of frame magnitudes over the frames scheduled for that symbol (linear magnitude combining, as in Pete's `runTest.m`; power combining is an accepted alternative with equivalent performance and is what the ORI AWGN check assumes).
- Decision: argmax over the 4096 tones. Symbol 10 (the last) carries only 7 data bits; restricting its argmax to the 128 tones with the 5 padding bits zero is a documented option (off = faithful to ORI).
- Unpack 11 symbols MSB first to 132 bits, take the first 127, BCH-decode (up to 3 bit errors), split 90 + 16, check the CRC.

6.4 Frame and schedule timing

- Frames are numbered k = 0, 1, 2 … over the frames the session transmits. The schedule's chunk table gives each chunk its first and last frame and its transmit start t_c (UTC); frame k of that chunk occupies transmit time [t_c + (k − k_first) × T_frame, t_c + (k − k_first + 1) × T_frame). A continuous session is one chunk with t_c = t_0.
- Symbol index m(k) = floor(k / N_frames) mod N_sym; repetition r(k) = floor(k / (N_frames × N_sym)).
- A transmitter emits only the frames in the chunk table; between chunks it is silent and no frames are consumed.
- A receiver expects frame k at its transmit time + RTT(t), where RTT is evaluated at the transmit time from the schedule's ephemeris, and files it into accumulator (r, m(k)). The frame grid need only be right to about one frame (section 4.3).

- Optional pilot: the first N_pilot frames (default 40) of every on-window carry tone d_pilot (default 2048) instead of the message symbol; the receiver excludes them from the symbol accumulators.

6.5 Doppler convention

The schedule names the receiver. The transmitter pre-compensates so that the tone arrives at the receiver at f_RF(d) as defined in section 6.2: it transmits at f_RF(d) − f_D(t), where f_D is the two-way (monostatic) or uplink-plus-downlink (bistatic) Doppler for the named receiver at the echo's arrival time. A receiver with the schedule file applies no bulk correction, only residual tracking. A receiver without the transmitter's schedule applies its own ephemeris for the full two-way Doppler.

7. ICD part B — the station

These are the interfaces between the modem software and the Haswell station. Values in square brackets are the modem's assumptions; the station team owns the actual numbers and the entries marked TBD need them.

7.1 Radio

Interface	Specification
Radio	Ettus USRP B210, one unit, owned exclusively by the modem process during a session. Tunes 70 MHz to 6 GHz; the dial frequency is a schedule parameter (1296, 1299.5, 2304, 2400 MHz, and others)
Transmit port	TX/RX A. Venus: to the 20 W driver of the amplifier chain below; B210 output [+10 dBm maximum], the modem runs A = 0.8 (−2 dB) at full TX gain unless the driver's input requirement says otherwise. EME tests: directly to the feed through the transmit/receive switch, no amplifier; output set by TX gain to the wanted C/N0 (section 4.6)
Transmit chain, 23 cm	B210 → 20 W driver amplifier in the control room (a station build) → LMR-600 coax to the feed, 8.8 dB loss at 1299.5 MHz (measured 2026-10-10: 17.5 dB round trip through the two shorted feedlines, halved) → final SSPA at the feed, whose built-in pre-driver stage makes full power from 2 W → feed (Rick, 2026-09-28). The numbers close: +43 dBm at the driver, 33 dB above the B210's +10 dBm maximum, less the coax loss leaves the +33 dBm (2 W) the amplifier needs (Alex Nersesian, 2026-09-10). The SSPA data excerpt's 1280 to 1300 MHz, 1200 W CW peak output, 20 to 30 W typical input describes the pallet behind the pre-driver. TBC with the station team: the measured coax loss and the pad that keeps the B210 from overdriving the driver (O4). The comb sits 25 to 48.5 kHz above the 1299.5 MHz dial, 0.45 MHz inside the amplifier's upper band edge. The package's built-in transverter (RF 1296 to 1298 MHz, IF 144 to 146 MHz) is not used

Interface	Specification
Receive chain, 23 cm	Feed → LNA → bandpass filter (optional, recommended by the station team) → RX2 A. The filter keeps out-of-band power off the B210 front end; its passband must cover 1299.5 MHz plus 0 to 50 kHz, and its loss is charged to the receive line loss of the link budget (0.5 dB assumed)
Package modules	Two of the EVE25 package's three modules are used, the final SSPA and the CMU (its control and monitoring unit), both mounted at the feed (Rick, 2026-09-28); the RF module, which is the transverter, is not (Alex Nersesian, 2026-09-10)
Receive port	RX2 A, from the LNA. RX gain set for the receiver noise to sit 10–15 dB above the B210 floor (verified live with the tone-strip display)
Cabling to the RF package	The B210 has separate transmit and receive ports, so the runs to the RF package at the feed are: one LMR-600 coax carrying the 20 W drive from the control-room driver (8.8 dB loss at 1299.5 MHz), one coax carrying the LNA output to RX2 A, and the two key lines from the USB relay board, TX key to the amplifier and LNA key to the LNA (Rick, 2026-09-10 and 2026-09-28). The GPS clock sits beside the B210 with two short coax runs (10 MHz to REF IN, PPS to PPS IN) and a USB cable to the host; its GPS antenna needs a sky view. TBD: run lengths, the measured losses (8.8 dB one way at 1299.5 MHz on the transmit run, measured 2026-10-10), and connector types at each end
Sample rate	32 × modem rate: 1,504,706.56 S/s (Variant A) or 786,432 S/s (Variant B); actual UHD rate read back (the bench B210 runs 1,504,707.01 S/s, 0.3 ppm high) and the residual absorbed by the frequency tracker
Tuning	f_dial with the verified LO-offset method inherited from the Workbench, in both directions: the LO is parked 300 kHz below the dial frequency so its leakage sits far outside the receive front end's passband and never aliases into the comb (with the LO on the dial frequency, its leakage 25 kHz below tone 0 would fold into the comb after decimation). If the offset cannot be applied honestly the radio says so and the session tool decides
Reference	The station reference is a Leo Bodnar Precision GPS Reference Clock (the dual-output model, USB HID; D23), replacing the HP5065A rubidium and the site NTP server that failed in September 2026. Output 1, 10 MHz at drive level 1 (16 mA, about +11 dBm into 50 Ω), to the B210 REF IN, whose limit is +15 dBm. Output 2 disabled: in that state the OUT2 connector carries the GPS receiver's 1 PPS (3.3 V CMOS, 200 ms high; measured 2026-09-12 with firmware 1.7), to the B210 PPS IN, whose window is 1.8 to 5 V. The modem programs exactly this setting over USB at every start (`eve/gpsdo.py`, `--gpsdo`), waits for satellite and PLL lock (60 s limit; the PLL drops for a few seconds after reprogramming), and refuses to start a session unless the clock is locked and the B210's `ref_locked` reads true (the sensor reports lock to an external or GPSDO reference only; it reads false on the internal reference). Verified on the bench 2026-09-12: locked, timed from the PPS, decoded (section 5.4). Any GPSDO with a 10 MHz output between +3 and +15 dBm and a 1.8 to 5 V PPS would serve instead

Interface	Specification
Time	USRP time set to UTC at a PPS edge, the second number taken from the host's NTP clock (internet NTP at the site, good to well under half a second, which is all the PPS-edge set needs); verified against a second PPS before the session (bench: set error 0.000000 s). Without a PPS the modem sets the time from the host clock alone (`--time-source host`, tens of milliseconds, inside the one-frame tolerance) and says so in the session log. The sample clock is then the schedule clock: the transmit stream starts at a device time given by a `tx_time` tag and the receive stream at the same time, so sample n is device time t_0 + n / f_s exactly
Device open	The application opens the B210 in a fresh worker process for every run (section 5.1, `worker.py`): on this Windows build the USRP source constructor faults about one time in seven with nothing else on USB, and a second source in one process faulted every time on the desktop; the worker settles 2 s, opens the device before it talks to the GPS clock over USB, and the application retries a failed open up to three times. About 13 s per open with the FPGA image load
Arming	Starting the flowgraph with both USRP streamers takes about 4 s on the Windows bench, so the session arms the streams [8 s] before the first scheduled sample. A late timed start drops the whole transmit stream and the receive start command, which is how this number was learned

7.2 Keying and sequencing

Interface	Specification
Keying outputs	Two signals, TX key and LNA control, sequenced by the modem (D24). At DSES they are the two relays of the USB relay board (DIUSTOU DSTUR-T20, 2 channels, optocoupler isolated, USB-C, native USB serial; `docs/hardware/diustou_dstur_t20.md`): relay 1 = TX key, relay 2 = LNA control, each an SPDT contact (COM, NO, NC; 10 A), on separate lines to the amplifier and to the LNA at the feed. The modem drives the same two signals in parallel on the B210 J504 GPIO (10-pin 2.54 mm header; on the DSES clone the front-panel 2x5 header labeled with the GPIO numbers): GPIO_0 = TX key, GPIO_1 = LNA, 3.3 V LVCMOS, for a station with its own external sequencer at the feed, as ORI's, and only through an external isolating circuit, never straight to station inputs; DSES does not use the GPIO outputs (Rick, 2026-09-28). Polarity: energized / high = transmit, energized / high = LNA off; both released / low = receive, so a board that is unplugged, a PC that is off, or lines that are not driven leave the feed in receive. GPIO_0 alone may drive an external sequencer (DB6NT style), GPIO_1 then being ignored. The board is found on whatever COM port it has (a status query must answer); a run without it proceeds on the GPIO lines and the operator is told, which at DSES, where the GPIO lines are not wired, keys nothing. Host-timed (D22); a keying fault is logged and shown, the run continues under the operator's eye; a watchdog releases the transmitter first if a chunk overruns
Sequencer timing	LNA off; guard [50 ms default, Setup]; TX key asserted; [T_lead = 200 ms]; first non-zero sample ... RF stopped; [T_lag = 100 ms]; TX key released; release [50 ms default]; LNA on. Abort and session end take the same way out, transmitter first. The guard and release times are operator settings until the station's LNA and amplifier requirements are measured (O5)
Duty limits	The modem enforces T_on ≤ [300 s] and T_off ≥ [240 s] per chunk regardless of the schedule; a schedule violating them is refused. TBD: the amplifier's true thermal limits and whether 4-minute chunks are acceptable. The thermal test needs a 2 kW 50 Ω load with a 7/16 DIN connector, which the station does not yet have (O6)
Abort	Operator abort or any fault (reference unlock, underrun burst, USB error) releases the key immediately and logs the frame number
EME cadence	Monostatic Moon operation alternates transmit and receive every ≤ 2.5 s. TBD: whether the station's transmit/receive switching can follow that; if not, EME runs bistatic with a second receive antenna, or DSES transmits only and a partner receives

7.3 Feed and pointing

Interface	Specification
Feed	23 cm feed retuned from 1296 to 1299.5 MHz for 2026 (an easy retune per Alex Nersesian, 2026-09-10); 13 cm feed (2304 / 2400 MHz) when that package exists. A feed change is a station operation; the modem does not control feeds
Pointing	The modem does not steer the dish. It computes and displays Venus azimuth and elevation from the ephemeris for the operator. The measured 0.15° boresight offset is 0.7 dB two-way at 23 cm (0.88° beam) and 2.2 dB at 13 cm (0.50° beam); the pointing corrections memo of 2026-09-07 covers it

8. ICD part C — data and files

8.1 Schedule file

One JSON document per session, produced by `schedule.py` and shared with any partner station. It is the complete contract; a receiver needs nothing else.

```
{
  "schema": "dses-eve-schedule/1",
  "session_id": "DSES-EVE-20261024-A",
  "target": "venus",                      # venus | moon
  "epoch_utc": "2026-10-24T15:30:00Z",     # frame 0 transmit start
  "transmitter": {"site": "DSES Haswell", "lat": 38.380833, "lon": -103.156111,
"alt_m": 1311},
  "receiver":    {"site": "DSES Haswell", "mode": "monostatic"},
  "rf": {"f_dial_hz": 2304000000, "f_if_hz": 25000},
  "waveform": {"variant": "A", "r_bw_hz": 2.87, "n_fft": 16384, "m": 4096,
"n_frames": 473,
               "n_sym": 11, "bch": [127, 106], "crc": "CRC-16-CCITT",
               "bit_order": "msb_first", "amplitude": 0.8, "phase": "continuous"},
  "message": {"text": "K0PRT K0PRT", "payload_bits": "<106 bits, Appendix C>",
              "codeword_bits": "<127 bits, Appendix C>",
              "symbols": [1203, 80, 1317, 1056, 1203, 80, 1317, 1031, 289, 3894,
3168]},
```

```
  "repeat_count": 5,
  "pilot": {"enabled": true, "n_frames": 40, "tone": 2048},
  "chunks": [ {"index": 0, "frame_first": 0, "frame_last": 688,
               "tx_start_utc": "…", "tx_stop_utc": "…",
               "rx_start_utc": "…", "rx_stop_utc": "…"}, … ],
  "doppler": {"model": "horizons", "table": "horizons_venus_haswell_20261024.csv",
              "convention": "tx_precompensated_for_receiver"},
  "limits": {"t_on_max_s": 300, "t_off_min_s": 240},
  "generated_by": "dses-eve 0.1", "generated_utc": "…"
}
```

The symbols listed are the transmitted symbols; a partner receiver may use them to score its decode directly.

8.2 Receive archive

`<session_id>_<NN>.eve.iq` — complex64, little-endian, interleaved I/Q at the modem rate with tone 0 at DC, one file per receive window (NN = chunk index), plus `<session_id>_<NN>.json` (`schema: dses-eve-archive/1`) with: the start of the first sample as device time and UTC (from the radio's `rx_time` tags), the receive window, sample rate and datatype, sample count, the first frame number and the first sample's offset into it in frames, f_dial, f_IF, whether the transmitter pre-compensated and whether the model Doppler was removed on receive, the radio description, the overflow gap count and list, and the waveform parameters. The archive is what the offline decoder reads and what is shared for independent decoding. It is written at the modem rate at baseband deliberately: an IF-offset stream at the modem rate would alias, since the comb is half the modem rate wide.

8.3 SigMF interchange

Export writes ORI's format: `core:datatype cf32_le`, `core:sample_rate`, the `ori:design` block with the same keys as ORI's generator, per-symbol annotations, and an additional `dses:schedule` block that embeds the schedule file. Import accepts ORI's files as produced by `eve_tx_sigmf.py` and plays them through the DSES transmit chain unchanged, for cross-checks against the streaming synthesizer.

8.4 Session log and report

Every session writes `<session_id>_session.json` (start and finish UTC, radio description, key events with device times, chunks keyed, frames sent, the receive report with gap counts and file list, the live decode, abort state and reason, the schedule and the options that ran) and, after the offline decode, a one-page PDF

report in the DSES house style: schedule summary, tone-strip image per symbol, decoded symbols against the transmitted ones, BCH corrections used, CRC result, and estimated C/N0 from the accumulators. The report is the deliverable of a session.

Every run from the application also writes `<session_id>_report.pdf` beside the log: the verdict of the offline decode, the decisions with margins per pass, the chunk timeline with key events, the per-window synchronization (pilot offset, tracker residual, gaps), and the key-event list. The application shows it when the run ends; `Re-decode` rebuilds it from the archived windows.

9. ICD part D — the Workbench boundary

The modem is a separate project. The interface to the DSES Radio Astronomy Workbench is a code-sharing boundary, not a runtime one:

- The Workbench's B210 classes (device discovery, `UhdB200Source`, the verified LO-offset tune path, the deep-buffer and real-time-mode helpers) are factored out of `dses_workbench.py` into an importable module that both projects use. Done 2026-09-11: `dses_radio.py` in the Workbench repository, shipped with it; the Workbench imports the same names and its behavior is unchanged; the modem finds the Workbench clone (or the `DSES_WORKBENCH` variable) and imports the module from there. New in it for the modem: the tune path as a function usable on a transmit sink, reference and PPS time-set helpers, and the GPIO keying line.
- The Workbench's `FilterbankSink` pattern (a GNU Radio sink with a deep queue and a close method that reports gaps) is the template for `EveRxSink`.
- The pulsar planner's site and visibility code is reused for the Venus and Moon windows.
- The Workbench keeps its rule that its own transmitter is locked at minimum gain. Real transmit drive exists only in the EVE modem, behind the interlocks of section 7.2.
- One B210 belongs to one process. During an EVE session the modem owns the radio; the Workbench is not running on it.

10. Decisions and open issues

10.1 Decisions taken in this revision

#	Decision	Rationale
D1	Stream the waveform; SigMF is export/import only	Chunking, live Doppler, no multi-GB files; nothing lost since schedule + symbols regenerate the IQ

#	Decision	Rationale
D2	Monostatic baseline, 4-minute chunks	The only mode DSES controls; European receivers at 1299.5 MHz are the upside via the schedule file. 4 min stays under both the round trip and the PA limit; 64 min per message
D3	ORI Python conventions are the air-interface spec; MATLAB set selectable for simulation only	ORI: the Python is the current implementation
D4	T_sym defined as 473 whole frames; modem rate defined as 16,384 × 2.87 Hz	Removes the two non-integer artifacts in the ORI numbers
D5	GPS time and GPSDO reference replace the maser	Non-coherent detection needs frame assignment and frequency, not phase
D6	Doppler pre-compensated on transmit for the named receiver, residual tracked on receive	79 Hz per symbol uncorrected
D7	Pilot frames on for EME and early Venus sessions	Cheap live check of timing and Doppler
D8	Receiver is offline-first; raw archive always written	Any session re-decodable with a better receiver
D9	Separate project; Workbench radio classes factored into a shared module	Different operational character; keeps the Workbench release train clean
D10	Phase-continuous symbol hops	Cleaner for the Class-C chain; invisible to a non-coherent receiver
D11	Frequency-agile modem: dial frequency per schedule; ORI waveform parameters unchanged on every band	23 cm in 2026, 13 cm later, EME on both; interoperability with the 1299.5 MHz stations
D12	EME tests use the bare B210 as the transmitter	+12 to +16 dB-Hz off the Moon with no amplifier; validation decoupled from amplifier schedules
D13	Variant B (1.5 Hz bins, 247 frames) defined for DSES monostatic 23 cm; Variant A for any session with a partner receiver	+1.1 dB where DSES needs it most; schedule names the variant
D14	Message text = K0PRT K0PRT, a schedule parameter	Station callsign, fills the 90-bit field exactly
D15	Link budget rows come from ORI's own classes, run by `link_budget/dses_cases.py` at the 2026 distance	Reproducible; one command when a station number changes

#	Decision	Rationale
D16	The B210 generates 1299.5 MHz directly; the EVE25 transverter is bypassed and a 20 W driver in the control room feeds, through 8.8 dB of LMR-600 (measured 2026-10-10; about 10 dB was assumed), the final SSPA at the feed, whose pre-driver makes full power from 2 W	The transverter covers 1296 to 1298 MHz only; the SSPA covers 1280 to 1300 MHz (Alex Nersesian and Rick, 2026-09-10); driver rating and amplifier location corrected by Rick, 2026-09-28
D17	The link budget is stated at ORI's static albedo (0.152) and at ORI's date-resolved albedo for conjunction (0.117)	Michelle Thompson's review of 2026-09-10: the notebook resolves distance and albedo per date; DSES plans on the value behind the CAMRAS cross-check and carries the 1.1 dB pessimistic case
D18	Frames count transmitted frames; the chunk table maps frame ranges to UTC	Off periods consume no frames, so a message is 5,203 transmitted frames however it is chunked (sections 4.1, 6.4)
D19	Timing of record is GPS plus the ephemeris; the pilot measures frequency offset and presence and checks the epoch to a whole frame	A steady tone carries timing information only at its edges; a one-frame grid error costs 1/473 (sections 4.3, 4.5)
D20	Two-stage receive front end, flat to 99.5 percent of the bandwidth	The comb fills the modem-rate Nyquist band exactly; one stage cut the top tones by 8 dB (section 5.3)
D21	Bistatic transmit is chunked by the amplifier's duty limits	The 30-minute message exceeds the 5-minute on-limit; the partner's non-coherent receiver does not care about gaps (section 3.3)
D22	Host-timed keying with an 8 s arming lead for the radio streams	Timed GPIO did not defer on the bench build; flowgraph start with two streamers takes about 4 s (sections 7.1, 7.2)
D23	The station reference is a Leo Bodnar GPS reference clock, programmed by the modem: output 1 = 10 MHz at level 1, output 2 disabled = 1 PPS; internet NTP for the host clock	The HP5065A rubidium and the site NTP server failed (Rick, 2026-09-12); the clock's lock, the B210's lock to it, and the PPS-edge time set were proven on the bench the same day (section 7.1, 5.4)
D24	The modem is the station sequencer: it drives the TX key and the LNA control itself, on the two relays of a USB relay board (the DSES keying path), with the safe order and guard times; both signals released = receive. The B210 GPIO_0 / GPIO_1 carry the same two signals in parallel but are not used at DSES	The station has no sequencer (Alex Nersesian, 2026-09-14). Fail-safe by polarity: nothing driving the lines leaves the LNA active and the transmitter off. The GPIO pair serves a station with an external sequencer at the feed, as ORI's. Rick, 2026-09-23 and 2026-09-28 (section 7.2)

#	Decision	Rationale
D27	A Moon or Venus run transmits only when the whole comb (f_IF to f_IF + M x spacing above the dial) lies inside a US amateur band: the application refuses the Start, the session's preflight refuses the schedule, and the worker refuses the run (`bands.py`, 47 CFR 97.301 for the bands the B210 reaches)	The dial is a free number in the application and the comb reaches 48.5 kHz above it; a slip at the keyboard must not put a kilowatt outside the band. Rick, 2026-10-23
D26	A sky run is bounded by a stop time: the earlier of an operator-set UTC stop and the target's setting below a minimum elevation (10° default), and the start may be "when the target rises" above it, so a day's operation is one START pressed ahead of time; a run can be ended cleanly at a chunk boundary (the chunk in progress and its echo complete, nothing more keyed, decode and report follow)	The sessions had no stop at all: a run ended only when the repeat count was sent or on abort, and a day at Venus is a window of about 8 h above 10° that the passes must fit (the 2026-10-20 operating schedule). Rick, 2026-10-23 (section 4.2, `ops.py`)
D25	The modem carries its own bench signal generator: CW, two-tone or the EVE waveform, keyed and unkeyed at will through the sequencer until stopped, signal and level adjustable live (TX gain and a digital scale) or stepped on a timer, with a dry run on the simulated radio	Integrating the driver, the SSPA and the feed needs a source that keys and times like the modem; a laboratory generator does not exercise the sequencer wiring. Meter integration deferred (O18). Rick, 2026-09-23 (section 5.8)

10.2 Open issues

#	Issue	Owner	Needed by
O1	Confirm R_bw = 2.87 Hz and N_frames = 473 (vs 440 on the slide, 540 in MATLAB)	Pete Wyckoff / ORI	Before stage 2
O2	23 cm amplifier: the power actually delivered at 1299.5 MHz (rated 1200 W CW, −4.2 dB-Hz monostatic; the frequency is 0.5 MHz inside the top of its 1280 to 1300 MHz range) under the chunk duty cycle, and the receive Tsys. The retune question is closed: transverter bypassed, feed retunes (D16)	DSES station team (Alex, Roger)	Before Venus
O3	Closed in Rev C (D23): the Leo Bodnar GPS clock, 10 MHz at level 1 and the PPS from the disabled output 2, two short coax runs to the B210. Still to place at the site: the clock's GPS antenna with a sky view, and the host's internet NTP	DSES station team	Before EME test

#	Issue	Owner	Needed by
O4	Drive chain settled (Rick, 2026-09-28): a 20 W driver in the control room, LMR-600 to the feed, 2 W into the SSPA's built-in pre-driver. Coax loss MEASURED 2026-10-10 at Haswell: 8.8 dB one way at 1299.5 MHz (17.5 dB round trip through the two feedlines shorted at the feed, Mini-Circuits PWR-SEN-6GHS+), less than the 10 dB assumed, so the pre-driver saw more drive than planned; the B210 TX gain default for the Moon and Venus went from 55 to 53 dB on 2026-10-23 (Rick: the amplifiers were being overdriven). Still open: the driver's measured gain and 1 dB compression at 1299.5 MHz (2.3 W saturated on the bench, 2026-10-09) and the pad, so the drive at the pre-driver is known in dBm		
O5	Keying interface: CLOSED in principle by D24 (the modem sequences; relay contacts and GPIO lines defined in 7.2). Still needed from the station: what the LNA side switches (DC, a coax relay coil, or a logic input), the amplifier's own lead requirement, and the guard times to set; then whether 2.5 s alternation is possible for monostatic EME	DSES station team	Before EME test
O6	PA thermal limits: are 4-minute chunks with 4.5-minute cooldown acceptable for a 6-hour session? The test needs a 2 kW 50 Ω load with a 7/16 DIN connector, not yet on hand	DSES station team	Before Venus
O7	Solar noise at 6° separation: Tsys increase on top of the 23 cm shortfall (section 2.2)	Link budget (DSES / ORI)	Before Venus
O8	Whether ORI wants the receiver contributed back to `Python_Implementation`	ORI	After EME
O9	Bistatic sessions with Effelsberg: if offered, the exact mutual window and who compensates Doppler	ORI / DSES	If offered
O10	EME libration spread at 1296 MHz on the test date; choose R_bw for the test	DSES	Before EME test
O11	Tell ORI about Variant B (DSES-only 23 cm parameters, D13) and ask whether they want it in their generator as an option	DSES → ORI	Before EME test
O12	Transmit/receive switch at the feed for direct-B210 EME tests: relay type, LNA protection, switching time for the 2.5 s alternation	DSES station team	Before EME test
O13	13 cm band: 2304 or 2400 MHz, and the feed for it	DSES station team	Next apparition

#	Issue	Owner	Needed by
O14	The DEFCON group's receiver (over-the-air test and code check-in expected the weekend of 2026-09-12): obtain it when it lands in the ORI repository and cross-check it against the DSES receiver with the Appendix C test vector	DSES / ORI	When published
O15	Date-resolved albedo: ask ORI for ρ_eff on the March 2025 CAMRAS dates, to learn whether the validated value already reflects it, and for the 2028 window; raise at the ORI meetup of 2026-09-15	DSES → ORI	Before Venus
O16	Closed 2026-09-12: reference lock and the PPS-edge time set proven with the GPS clock of D23; transmit frequency on the 53230A within 0.03 Hz of nominal at 1296.025 MHz (`tools/eve_txcw.py`; bench note `docs/bench/gpsdo_2026-09-12.md`). Stage 4 complete	Rick	Before EME test
O17	The CAMRAS Venus echoes of March 2025 through the receiver (stage 3's remaining item)	DSES	Before Venus
O18	Signal generator (5.8): read the bench HP 8595E spectrum analyzer (the lab's power reference, behind a calibrated 40 dB 10 W pad) over GPIB at each sweep step and put the reading in the sweep report beside the TX gain, so the compression curve is recorded rather than copied by hand. The analyzer's measurement settings are the operator's and are not changed by the program	Rick	Bench integration of the RF package

Appendix A — MATLAB simulation versus Python implementation

For readers of the ORI repository. The two describe different signals; the air interface in section 6 follows the Python.

Parameter	MATLAB (EveDemo.m, May 2026)	Python (eve_tx_sigmf.py, Aug 2026)
FFT bin / Doppler spread	2.67 Hz	2.87 Hz
Tone spacing	5.34 Hz	5.74 Hz
Frames per symbol	540	473 (README: slide shows about 440)
Symbol length	202.25 s	164.794 s (472.96 frames)
Message time	37.1 min	30.2 min
Bit-to-symbol order	LSB first (`2.^(0:11)`)	MSB first

Parameter	MATLAB (EveDemo.m, May 2026)	Python (eve_tx_sigmf.py, Aug 2026)
Comb placement	every other bin of an 8192-point FFT, symmetric about DC	one-sided, 0 to 23.5 kHz above the dial frequency + 25 kHz
Payload	106 random bits	90 message bits + CRC-16
Channel model	AWGN + Rayleigh ($\sigma = \sqrt{(2/\pi)}$, −1.05 dB), random phase per frame	none (analytic AWGN link check separate)
Receiver	simulated: magnitude sum over frames, argmax, BCH decode	none
BCH generator	octal 11554743 (MATLAB `bchenc` default)	same (`galois` default)

Appendix B — Timing arithmetic

- Frame: 1 / 2.87 Hz = 0.348432 s; 16,384 samples at 47,022.08 S/s.
- Symbol: 473 frames = 164.808 s = 7,749,632 modem samples.
- Message: 11 symbols = 5,203 frames = 1,812.9 s.
- 4-minute chunk: 240 s = 688.8 frames; the schedule rounds chunks to whole frames (688 frames = 239.7 s), so a message needs 5,203 / 688 = 7.56 → 8 chunks.
- Round trip 2026-10-24: 2 × 40.8 million km / c = 272 s; ephemeris-computed per session. JPL Horizons and astropy's built-in ephemeris differ by 230 km in range and 0.7 m/s in range rate at conjunction, which is 10 Hz (3.5 bins) at 2304 MHz: Horizons is the primary source, astropy the offline fallback (section 4.3).
- Doppler across one symbol at the peak rate: 2304 MHz, 0.48 Hz/s × 164.8 s = 79 Hz = 13.8 tone spacings; 1299.5 MHz, 0.27 Hz/s × 164.8 s = 45 Hz = 7.8 spacings. Across one frame: 0.17 Hz (0.06 bin) and 0.09 Hz.
- EME link with the bare B210 (+10 dBm, 18.29 m dish, mean Moon distance, radar cross-section 6.5 percent of the disc): path loss 271.2 dB at 1296 MHz and 276.2 dB at 2304 MHz; C/N0 = +12.2 dB-Hz (Tsys 60 K) and +16.2 dB-Hz (Tsys 76 K).
- Radio rate: 32 × 47,022.08 = 1,504,706.56 S/s; a 1 ppm rate error is 0.05 Hz at the top of the comb, absorbed by the residual tracker.
- Variant B: frame 1 / 1.5 Hz = 0.66667 s = 16,384 samples at 24,576 S/s; symbol 247 frames = 164.667 s; message 2,717 frames = 1,811.3 s; comb 4096 × 3.0 Hz = 12.3 kHz; radio rate 32 × 24,576 = 786,432 S/s. Doppler across one frame at 0.27 Hz/s: 0.18 Hz = 0.12 bin.

Appendix C — Reference test vector

Computed with ORI's `eve_tx_sigmf.py` (galois BCH, CRC-16-CCITT, MSB-first packing) for the DSES message. Any implementation of either variant must reproduce these symbols.

Item	Value
Message text	`K0PRT K0PRT` (11 characters)
90 message bits	`01001011 00110000 01010000 01010010 01010100 00100000 01001011 00110000 01010000 01010010 01010100 00`
CRC-16-CCITT (16 bits)	`0001110001001000` (0x1C48)
127-bit codeword (106 payload + 21 parity)	`01001011001100000101000001010010 01010100001000000100101100110000 01010000010100100101010000000111 000100100001111100110110110011`
Symbols d0 … d10	1203, 80, 1317, 1056, 1203, 80, 1317, 1031, 289, 3894, 3168
Variant A tones (d × 5.74 Hz)	6905.22, 459.20, 7559.58, 6061.44, 6905.22, 459.20, 7559.58, 5917.94, 1658.86, 22351.56, 18184.32 Hz
Variant B tones (d × 3.0 Hz)	3609, 240, 3951, 3168, 3609, 240, 3951, 3093, 867, 11682, 9504 Hz

The repeated callsign shows in the symbols: the first three symbols (1203, 80, 1317) recur as symbols 4 to 6, because 48 bits of message repeat exactly 48 bits later.

Acknowledgments

This modem exists because the Open Research Institute (ORI) did the hard part first and published it under the GPL. **Pete Wyckoff, KA3WCA**, designed the Spiral #2 waveform: the 4096-ary FSK with 2.87 Hz bins, the 473-frame non-coherent symbol, the BCH(127,106) code, the frame channel model and the analytic error-rate table that sized the whole link at 0 dB-Hz. Everything in sections 4 and 6 of this document is his design restated for our station; where DSES departs from it (Variant B, the pilot, the chunking) the departures are labeled as ours. **Michelle Thompson** wrote ORI's Python implementation, the transmit generator and the AWGN link check that this modem's core is verified against bit for bit (Appendix C), maintained the link-budget classes we run unchanged (section 2.2), supplied the date-resolved Venus distance and the dynamic albedo that corrected our budget, and answered every question about which conventions were authoritative. Her code is the air interface this document specifies. ORI's open repository, its meetups and its willingness to have DSES build a receiver around its waveform are what made a Venus attempt from Haswell possible in one season. We could not have done this without them, and we hope the receiver and the station machinery here are a useful return.

On the DSES side, Alex Nersesian, K6VHF, Roger Oakey, W3MIX, Bill Miller, Myron Babcock, Paul Sobon, David Wilson, AA0RS, William Thomas, WT0DX, Ray Uberecken and Darryl Hambly reviewed the drafts, built and measured the station hardware this document interfaces to, and moved the dish. The DEFCON group working with ORI on a receiver of their own gave us a second implementation to compare against (O14).

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Document history

Revision	Date	Change
Rev A draft 1	2026-09-10	Initial design description and ICD
Rev A draft 2	2026-09-10	Band plan: Venus 2026 at 1299.5 MHz with the 23 cm package, 13 cm (2304 / 2400 MHz) later, EME tests on both bands with the bare B210; link budget per band (section 2.2), section 2.4, D11 – D12, O11 – O13
Rev A draft 3	2026-09-10	Rick's review: link budget recomputed row by row with ORI's classes at the 2026 distance (`link_budget/`); Variant B for DSES 23 cm monostatic (2.4, 6.1.1, Figure 2, D13); message K0PRT K0PRT and Appendix C test vector (D14); US spelling; table and paragraph pagination rules; narrower register columns
Rev A draft 4	2026-09-10	Table pagination (header keeps with first row, short tables whole); the monostatic-23 cm verdict with passes to combine; the 2028 apparition (geometry and link budget); beamwidth figures corrected (0.88° at 23 cm, 0.50° at 13 cm)
Rev A draft 5	2026-09-10	Issued to the EVE team for review (nine recipients, 17:57 MDT); section 7.1 gains the B210-to-RF-package cabling row (two coax plus key line) from the issuing email
Rev B	2026-09-11	Team review comments incorporated. Michelle Thompson (ORI): the notebook's date-resolved distance (Skyfield, 40.81 million km on 2026-10-25) and dynamic Venus albedo (0.117 at conjunction, −1.1 dB) in section 2.2 (D17, O15); ORI's DEFCON-group receiver noted (section 1, O14). Alex Nersesian (DSES): the transverter covers 1296 to 1298 MHz only and is bypassed (D16); SSPA 1280 to 1300 MHz, 1200 W CW, at least 2 W drive; LNA sequencer, LNA DC control, 2 W driver, and receive bandpass filter to be built; a 2 kW 7/16 DIN load for the thermal test; the feed retunes (sections 2.3, 7.1 to 7.3, O2, O4 to O6). 1200 W rows in the link budget and Figure 2

Revision	Date	Change
Rev C	2026-09-12	Updated from the implementation of 2026-09-11 (modem core, ephemeris, schedule, synchronization, radio side, operator display; 36 tests; B210 loopback bench decoded): frame numbering and chunk-table semantics (4.1, 6.4, D18); the pilot's real capability and the one-frame timing tolerance (4.3, 4.5, D19); two-stage receive front end (5.3, D20); bistatic chunking (3.3, D21); host-timed keying and the 8 s arming lead (7.1, 7.2, D22); module table, validation status column, archive and session-log contents as built (5.1, 5.4, 8.2, 8.4); the shared radio module done (9); O16, O17. Same day: station reference decided after the Haswell HP5065A and NTP server failed: Leo Bodnar GPS reference clock, output 1 = 10 MHz at level 1 to REF IN, output 2 disabled = 1 PPS to PPS IN, programmed and checked by the modem (`gpsdo.py`, `--gpsdo`); host-timed fallback stated (4.3, 5.1, 7.1, D23); O3 closed; bench with the B210 locked and timed from the clock, both passes decoded, transmit frequency on the lab counter within 0.03 Hz (5.4); O16 closed, stage 4 complete. Application `eve_app.py` (5.1, 8.4): modes, remembered settings, report PDF, tooltips; keying pins named (7.2)
Rev C addendum	2026-09-23	D24 (the modem is the sequencer: TX key and LNA on the USB relay board and GPIO_0/1 in parallel; 7.2 keying outputs and sequencer timing rows; O5 narrowed); the relay board identified as the DIUSTOU DSTUR-T20 and bench-checked; the signal generator run mode for the RF package integration (5.8, D25, O18).
Rev C addendum (Rick)	2026-09-28	Station corrections — the driver is a 20 W stage, not 2 W; the 1200 W SSPA and CMU are mounted at the feed; keying is by the USB relay board's two relays only, the B210 GPIO pair driven in parallel but unused at DSES (1, 2.2, 3.2, 5.8, 7.1, 7.2, D16, D24, O4); Figure 3 redrawn. Same day, 15:10: the 20 W driver sits in the control room because it drives about 10 dB of LMR-600 to the feed, where the SSPA's built-in pre-driver makes full power from 2 W (1, 7.1, D16, O4, Figure 3)
Rev C addendum	2026-10-07	The ARDC acknowledgment required by Section 10 of the grant agreement added to the header, Acknowledgments, Operator's Guide, README, LICENSE and the About dialog
Rev C addendum	2026-10-20	The pilot length as a per-chunk operator setting, capped to the Moon chunk (4.5), after the first full-length EME run from the station PC (2026-10-20 UTC) found the schedule's timestamp text dropping a second in one stamp per thousand (fixed, application 1.0.10)

Revision	Date	Change
Rev C addendum (application 1.0.11)	2026-10-20	The application's Moon and Venus defaults follow D13 (Variant B; interop pinned to Variant A)
Rev C addendum (application 1.0.23)	2026-10-23	On-air band limit for the Moon and Venus modes: the whole comb inside a US amateur band, refused at Start, in the session preflight and in the worker (D27, `bands.py`); the Moon and Venus TX gain default 55 to 53 dB, the feedline loss being 8.8 dB measured rather than the 10 dB assumed (7.1, D16, O4); same day 1.0.21: TX and RX gain change live in every run (recorded in the session JSON); 1.0.22: the Setup fields ignore the mouse wheel unless focused
Rev C addendum (application 1.0.17)	2026-10-23	The run bounded by a stop time and the elevation window, the "when the target rises" start, the clean stop at a chunk boundary, and the operating schedule table (4.2, 5.1 `ops.py`, 5.7, D26); same day, after the first Venus run from the station PC stalled on one transmit underflow at 14:52 UTC (chunks 1-3 sent, nothing after): the transmit stream re-times itself after an underflow (5.6, `gr_blocks.EveToneSource`); application 1.0.18 the same afternoon: the lag check moved out of the stream thread and the new burst leads by 4 s (1 s left the host no cushion), and the two per-sample Python loops in the transmit path (the tone lookup and the Doppler pre-compensation function) vectorized: 1.5x real time became 7x on the development PC, which is why the Raspberry Pi had no margin on Venus runs and plenty on the bench, where pre-compensation is off; 1.0.19 and 1.0.20 the same day: no label sets the window's minimum width (the station PC's window would not narrow), and the Keying group's switching choice survives a restart (it had come back as 'none' on every start since 2026-09-23, so the day's first Venus runs keyed neither the PA nor the LNA); a Moon or Venus START with no switching asks first